

# Transformers Learn Shortcuts to Automata

<https://arxiv.org/abs/2210.10749>



Bingbin



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# Algorithmic reasoning

Want to understand the reasoning capabilities & internal mechanisms of self-attention models.

**Question:** Assume that the variance of the first  $n$  natural numbers is 10, and the variance of the first  $m$  even natural numbers is 16. Compute  $m + n$ .

**Model output:** Let  $\sigma^2$  be the variance of the first  $m$  even natural numbers, and  $\tau^2$  be the variance of the first  $n$  natural numbers. Then, we have  $\tau^2 = \frac{n^2-1}{12}$  and  $\sigma^2 = \frac{m^2-1}{3}$ . We solve the system of equations:

$$\frac{n^2-1}{12} = 10$$
$$\frac{m^2-1}{3} = 16.$$

This translates into the system

$$n^2 = 121$$
$$m^2 = 48 + 1 = 49.$$

Therefore,  $n = \boxed{11}$  and  $m = \boxed{7}$ , so  $n + m = \boxed{18}$ .

Math: **Minerva**  
(Lewkowycz et al. 22)

**Question:** For every  $a, b, b \neq a$  prove that

$$\frac{a^2 + b^2}{2} > \left(\frac{a+b}{2}\right)^2.$$

**Model output:**

$$\frac{a^2 + b^2}{2} > \left(\frac{a+b}{2}\right)^2$$
$$\iff \frac{a^2 + b^2}{2} > \frac{a^2 + b^2 + 2ab}{4}$$
$$\iff a^2 + b^2 > \frac{a^2 + b^2 + 2ab}{2}$$
$$\iff 2a^2 + 2b^2 > a^2 + b^2 + 2ab$$
$$\iff a^2 + b^2 > 2ab$$
$$\iff a^2 + b^2 - 2ab > 0$$
$$\iff (a-b)^2 > 0$$

which is true, because the square of a real number is positive.



Code: **Codex / Copilot**  
(Chen et al. 21)

Input:

2 9 + 5 7

Target:

<scratch>

2 9 + 5 7 , C: 0

2 + 5 , 6 C: 1 # added 9 + 7 = 6 carry 1

, 8 6 C: 0 # added 2 + 5 + 1 = 8 carry 0

0 8 6

</scratch>

8 6

**Scratchpad** (Nye et al. 22)

**Coin Flip (state tracking)**

Q: A coin is heads up. Maybelle flips the coin. Shalonda does not flip the coin. Is the coin still heads up?

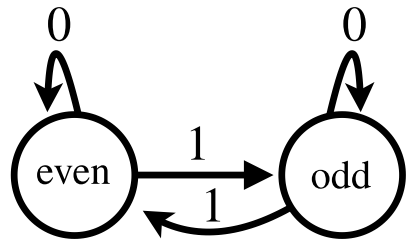
A: The coin was flipped by Maybelle. So the coin was flipped 1 time, which is an odd number. The coin started heads up, so after an odd number of flips, it will be tails up. So the answer is no.

**Chain-of-Thought** (Wei et al. 21)

# Algorithmic reasoning

Coin flip = **parity**

- Input (flip or not):  $\Sigma = \{1, 0\}$ .
- State (head/even or tail/odd):  $Q = \{0, 1\}$ .



$Q = \{\text{even}, \text{odd}\}$

$\Sigma = \{0, 1\}$

## Coin Flip (state tracking)

Q: A coin is heads up. Maybelle flips the coin. Shalonda does not flip the coin. Is the coin still heads up?

A: The coin was flipped by Maybelle. So the coin was flipped 1 time, which is an odd number. The coin started heads up, so after an odd number of flips, it will be tails up. So the answer is no.

a discrete-time dynamical system

$$\mathcal{A} = (Q, \Sigma, \delta)$$

states

inputs

transitions

$$q_t = \delta(q_{t-1}, \sigma_t)$$

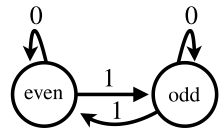
# (Semi)Automata

- Semiautomaton  $\mathcal{A}$ : a discrete-time dynamical system

$$\mathcal{A} = (Q, \Sigma, \delta)$$

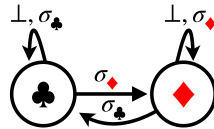
$$q_t = \delta(q_{t-1}, \sigma_t)$$

states    inputs    transitions



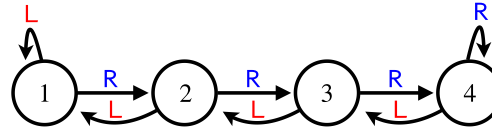
$Q = \{\text{even}, \text{odd}\}$   
 $\Sigma = \{0, 1\}$

parity counter



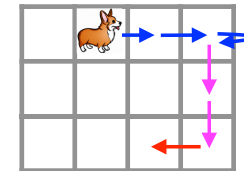
$Q = \{\clubsuit, \diamondsuit\}$   
 $\Sigma = \{\sigma_{\clubsuit}, \sigma_{\diamondsuit}, \perp\}$

1-bit memory unit



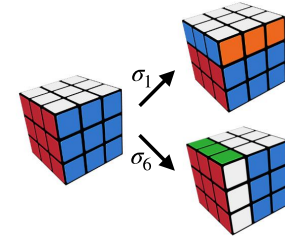
$Q = \{1, 2, 3, 4\}$   
 $\Sigma = \{L, R\}$

1D gridworld



$Q = \{1..3\} \times \{1..4\}$   
 $\Sigma = \{\leftarrow, \rightarrow, \uparrow, \downarrow\}$

2D gridworld



$Q = \{54 \text{ stickers}\}$   
 $\Sigma = \{6 \text{ face rotations}\}$

Rubik's Cube

- Automaton:  $(Q, \Sigma, \delta, \varphi)$ , outputs  $\tilde{q}_t = \varphi(q_t)$  (acceptance function)

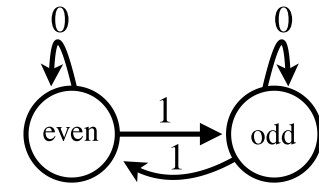
# Simulating automata

(Semi)automata: a discrete-time dynamical system

$$\mathcal{A} = (Q, \Sigma, \delta)$$

states    inputs    transitions

$$q_t = \delta(q_{t-1}, \sigma_t)$$



$Q = \{\text{even}, \text{odd}\}$

$\Sigma = \{0, 1\}$

e.g. **parity counter**

- Task: **simulate**  $\mathcal{A}$ : learn a **seq2seq function** for length  $T$ .
  - Input: sequence of **tokens**  $\sigma_1, \sigma_2, \dots, \sigma_T \in \Sigma$ .
  - Output: sequence of **states**  $q_1, q_2, \dots, q_T \in Q$ .

e.g. parity counter:  $\{\sigma_t\} = 01101$ ,  $\{q_t\} = 01001$ .

# Simulating automata with Transformers

🤔 *Can Transformers learn automata?*

- Automata is *recurrent*; Transformers are *non-recurrent* (*parallel*) and shallow.

Yes – **Shortcut**: solutions with  $o(T)$  sequential “steps/rounds”.

- Def: **longest path** in a computation graph (i.e. at most  $T$ ).
- e.g. recurrent nets: sequence length.
- e.g. Transformers: number of layers.



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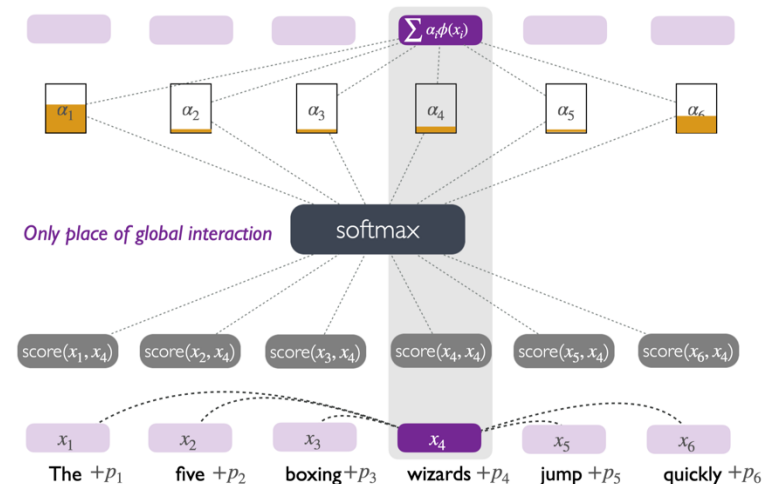
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Transformer recap

- $\forall i \in [T], x_i^{(l+1)} = \sum_j \alpha_{ij} x_j^{(l)}$ ;
- $\alpha_{ij} \propto \exp(\langle W_Q x_i^{(l)}, W_K x_j^{(l)} \rangle)$ .



# Simulating automata with Transformers

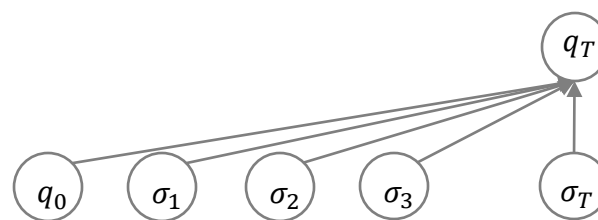
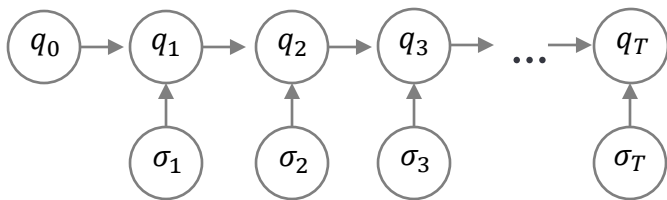
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Example: **parity** (prefix sum):  $q_t, \forall t \in [n]$ ,

- Iterative solution:  
 $q_t = q_{t-1} \oplus \sigma_t \in \{0,1\}.$
- Shortcut (parallel) solution:  
 $q_t = (\sum_{\tau \leq t} \sigma_\tau) \bmod 2 \in \{0,1\}.$




*Why shortcuts:*

- computational advantage;
- Unique & natural to Transformer.



# Transformers Learn Shortcuts to Automata

TL;DR: **Shallow** Transformers can simulate  $\mathcal{A} = (Q, \Sigma, \delta)$ .

- **Theory:** for any length  $T$ , Transformers with  $o(T)$  layers suffice.
  - $O(\log T)$ -layer simulation for *all*  $\mathcal{A}$  (also the lower bound for the general case)
  - $O(|Q|^2 \log |Q|)$ -layer simulation for all *solvable*  $\mathcal{A}$
  - $O(1)$ -layer simulation for **gridworld** 
- **Empirical study**
  - **Positive:** training shallow models SGD finds shortcuts in practice.
  - **Negative:** they're brittle OOD (distr on input symbols; other lengths).
  - **Fix:** *Scratchpad* training: force a Transformer to learn the recurrent solution.
- **Discussions** 💡

# Theory (as brain teasers)

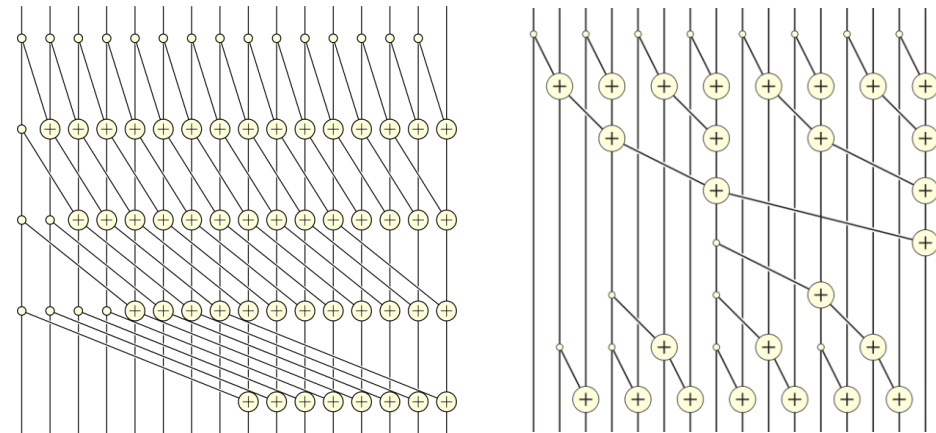
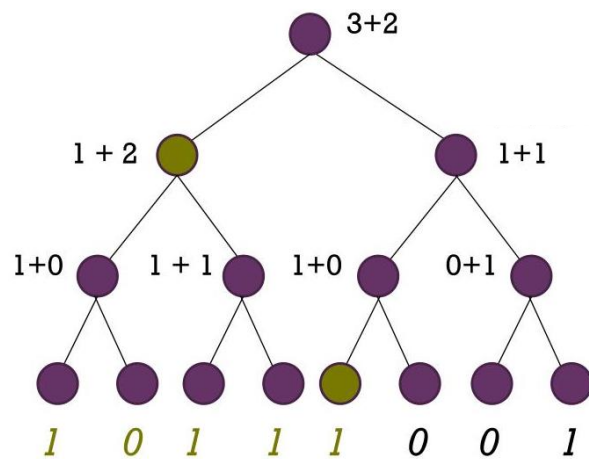
Solutions with  $o(T)$  computation depth

# Puzzle 1: Do shortcuts exist?

$\mathcal{A} = (Q, \Sigma, \delta)$ : (states, inputs, transitions)

Task: for each  $t \in [T]$ , compute  $q_t = \left( \delta(\cdot, \sigma_t) \circ \cdots \circ \delta(\cdot, \sigma_1) \right) (q_0)$ .

- Input token  $\sigma \rightarrow$  a function  $\delta(\cdot, \sigma): Q \rightarrow Q$ .
- Function composition (**associative**).



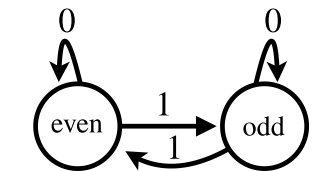
Parallel prefix sum (fig from Wikipedia)

# Puzzle 1: Do shortcuts exist?

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- Input token  $\sigma \rightarrow$  a function  $\delta(\cdot, \sigma): Q \rightarrow Q$ .
- Function composition (**associative**)  $\longleftrightarrow$  matrix multiplication



$Q = \{\text{even}, \text{odd}\}$

$\Sigma = \{0, 1\}$

parity counter



$$\delta(\cdot, 0) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \text{ (identity)}$$

$$\delta(\cdot, 1) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \text{ (swap)}$$

function composition

$$q_t = (\delta(\cdot, \sigma_t) \circ \cdots \circ \delta(\cdot, \sigma_1)) q_0$$

matrix multiplication

$$e_{q_t} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \cdots \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} e_{q_0}$$

Representation theory ([Chughtai 23](#)): can explain  $O(\log T)$ , but not what's coming up.

# Can we use $o(\log T)$ layers?

$\mathcal{A} = (Q, \Sigma, \delta)$ : (states, inputs, transitions)

We already have positive result on some tasks.

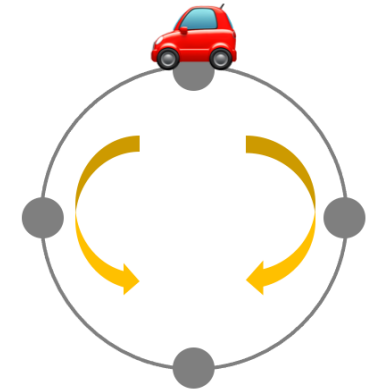
- Parity:  $q_t = (\sum_{i \in [t]} \sigma_i) \bmod 2$ : only need to **count** #1s.
- Counting suffices, if the function composition is **commutative**.
  - Corollary: any commutative compositions (abelian groups--explained later) can be represented with  $O(1)$  layers.

*Question:* Is there a solution with  $o(\log T)$  layers when ***non-commutative***?

## Puzzle 2: $\tilde{O}(|Q|^2)$ layers

Reversible car on a circular road:

- $\Sigma = \{D, U\}$  (drive, U-turn),  $Q = \{\text{car icon}, \text{car icon}\} \times \{0, 1, 2, 3\}$ .
- Consider input  $DDDUDDUUD\dots$ , starting from (car icon, 0).
- How to decide the current direction and position?
  - Direction = a parity task on  $U$ . (parity:  $\{1, -1\} \leftrightarrow \{0, 1\}$ )
  - Position = sum of signed counts (sign = parity of  $U$ ) **mod** 4.





$D \ D \ D \ U \ D \ D \ U \ U \ D$

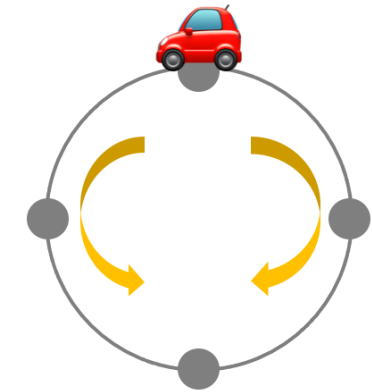
Parity:  $1 \ 1 \ 1 \ -1 \ -1 \ -1 \ 1 \ -1 \ -1 \rightarrow \text{car icon}$

Signed counts:  $1 \ 1 \ 1 \ 0 \ -1 \ -1 \ 0 \ 0 \ -1 \rightarrow 0$

# Solution 2: $\tilde{O}(|Q|^2)$ layers

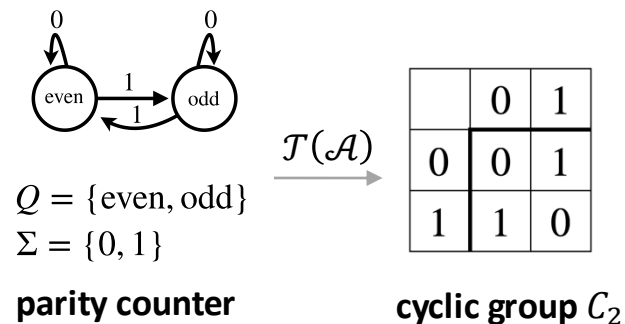
Reversible car on a circular road:

- $\Sigma = \{D, U\}$  (drive, U-turn),  $Q = \{0,1,2,3\} \times \text{car}$ ,  , .
- Decompose: 1) direction (parity), 2) position (signed sum mod 4).



Is such decomposition always possible? *Yes!*

Transformation group:  $\mathcal{T}(\mathcal{A}) := \{\delta(\cdot, \sigma) : \sigma \in \Sigma\}$  under composition.



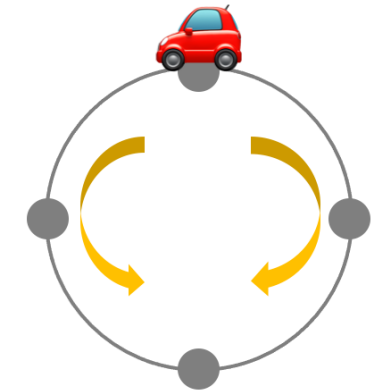
**Group  $G$ :** a set  $G$  with operation  $G \times G \rightarrow G$ .

- Associativity:  $(a \cdot b) \cdot c = a \cdot (b \cdot c)$
- Identity:  $a \cdot e = e \cdot a = a$
- Inverse:  $\forall a \in G, \exists b \in G$  s.t.  $a \cdot b = b \cdot a = e$

## Solution 2: $\tilde{O}(|Q|^2)$ layers

Reversible car on a circular road:

- $\Sigma = \{D, U\}$  (drive, U-turn),  $Q = \{0,1,2,3\} \times \{\text{car}, \text{car}\}$ .
- Decompose: 1) direction (parity), 2) position (signed sum mod 4).



Is such decomposition always possible? *Yes!*

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“Prime factorization” for groups:  $G \triangleright H_n \triangleright \cdots \triangleright H_1$  (Jordan & Hölder [ $\sim 1880$ ])

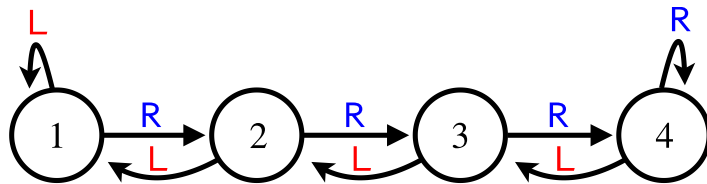
- $G \triangleright H$ :  $H$  is a normal subgroup of  $G$  ( $\sim$ factors).
- $H_{i+1}/H_i$  are simple groups ( $\sim$ prime numbers).



# What about *semigroups*?

$$\mathcal{T}(\mathcal{A}) := \{\delta(\cdot, \sigma) : \sigma \in \Sigma\} \text{ under composition}$$

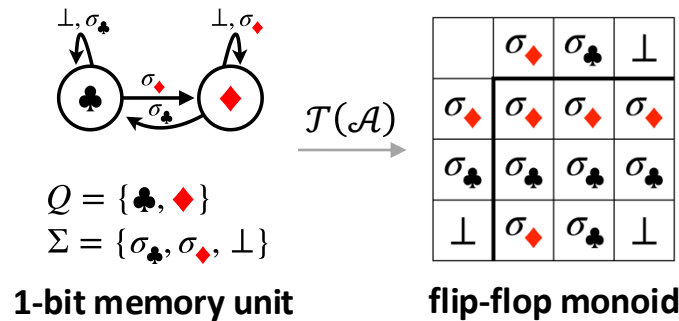
1d gridworld:  $\sigma_t = \text{L/R}$  steps,  $q_t = \text{location in a bounded room.}$



$$q_0 = 1, \quad q_t = \min(n, \max(1, q_{t-1} + 1))$$

e.g. **L****R****L****L****R****R****R****L****L**  $\mapsto$  1, 2, 1, 1, 2, 3, 4, 4, 3, 2

•  $\delta(\cdot, L) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$  is not invertible  $\rightarrow \mathcal{T}(\mathcal{A})$  is a *semigroup*.



**Semigroup  $G$ :** a generalization of group.

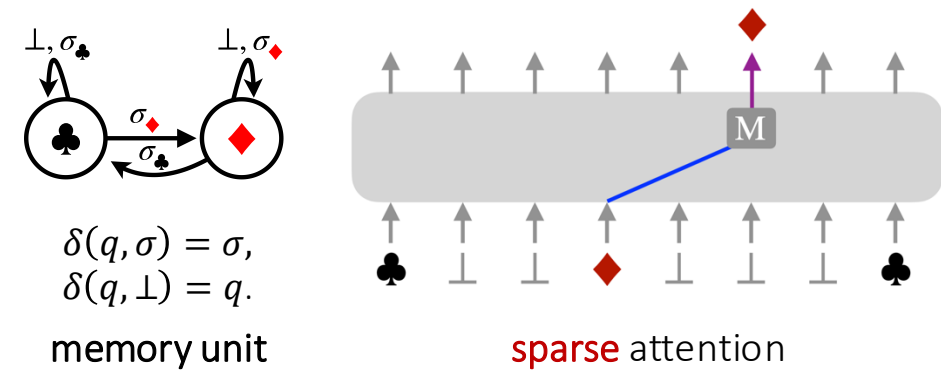
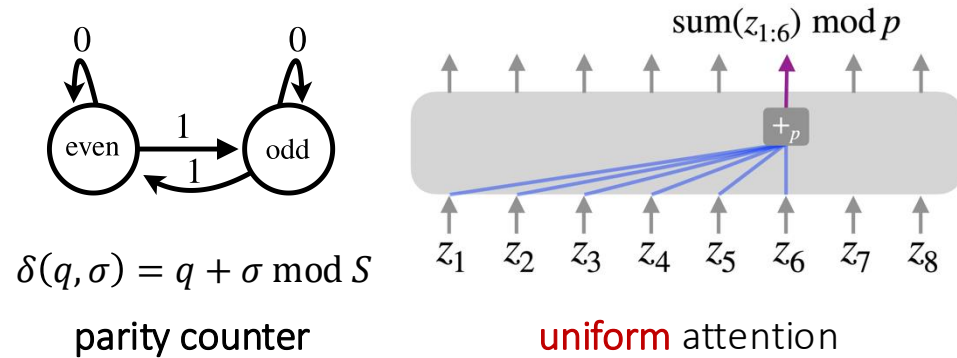
- Associativity.
- (+ Identity: a *monoid*.)

# Solution 2: $\tilde{O}(|Q|^2)$ layers

$$\mathcal{A} = (Q, \Sigma, \delta): (\text{states, inputs, transitions})$$

1d gridworld:  $\sigma_t = \text{L/R}$  steps,  $q_t = \text{location in a bounded room.}$

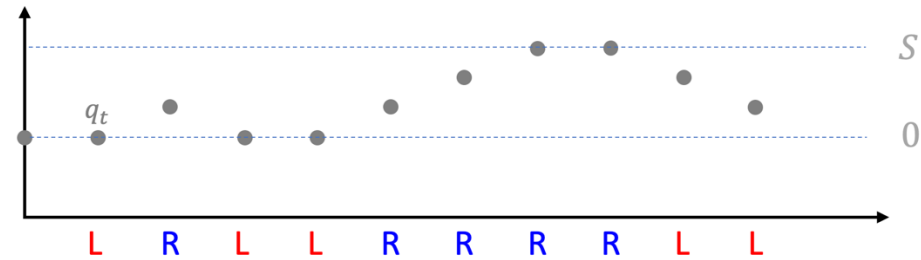
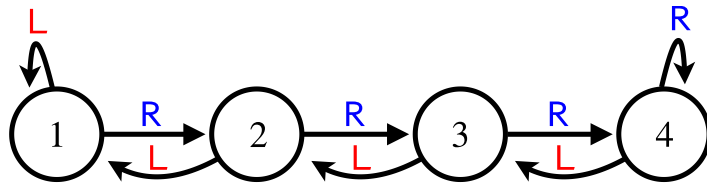
- **Krohn-Rhodes** (Thm 2): solvable semiautomata decomposed into **mod** + **reset**.
  - Solvable:  $H_{i+1}/H_i$  is commutative/abelian. [Recall Jordan & Hölder:  $G \triangleright H_n \triangleright \dots \triangleright H_1$ ]



*\*We do not claim that Transformers learn these decompositions in practice.*

# Puzzle 3: $O(1)$ layers?

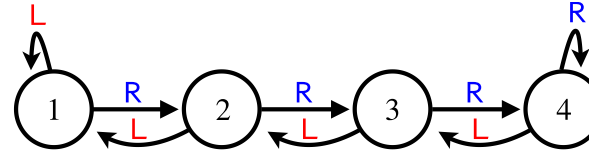
1d gridworld:  $\sigma_t = \text{L/R}$  steps,  $q_t$  = location in a bounded room.




**Puzzle:** design a parallel algorithm to compute  $\sigma_{1:T} \mapsto q_{1:T}$ .

- Hint: *boundary detection*: discard history; easy afterwards (prefix sum).

# Solution 3: $O(1)$ layer for

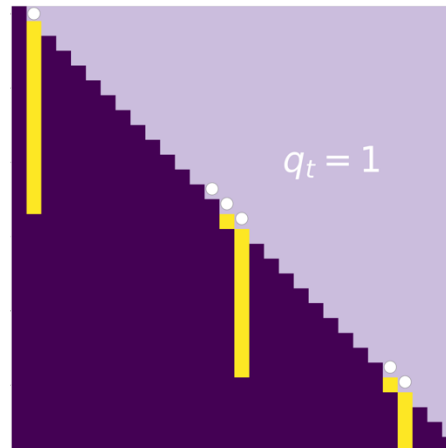


~~“You can only figure out whether you’re at a wall if you know  $q_{t-1}$ .”~~

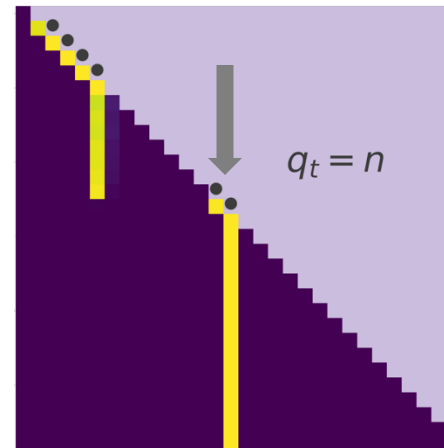
- Parallel boundary detection! 
- discard history; easy afterwards (prefix sum).



1<sup>st</sup> layer



4<sup>th</sup> layer, left boundary



4<sup>th</sup> layer, right boundary

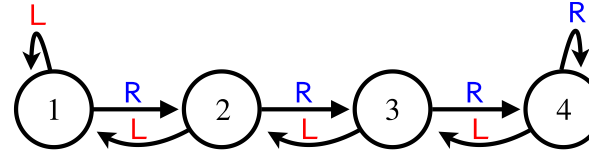
attention heatmaps

(GPT solved this before we did o o)

“mechanistic interpretability”

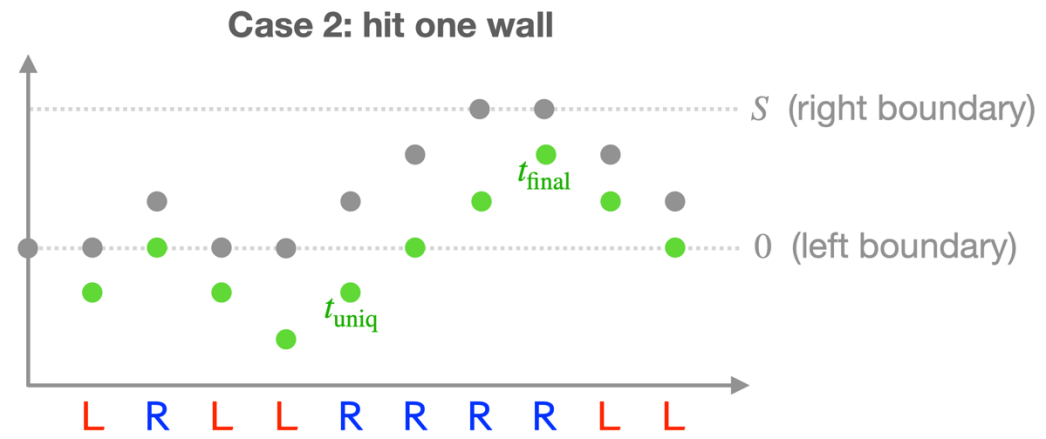
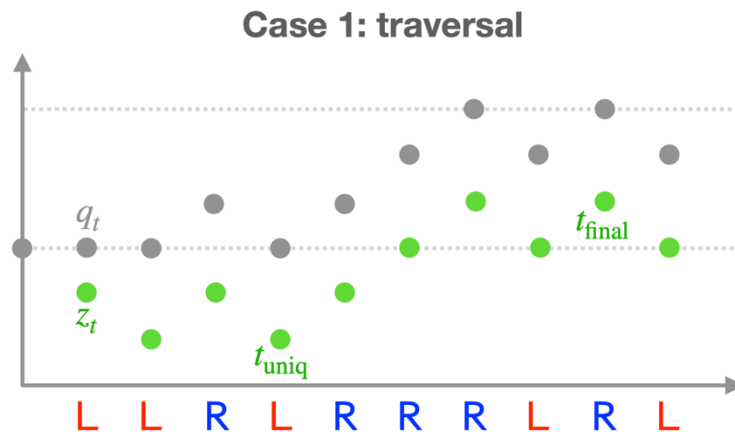
[Nanda & Lieberum '22]

# Solution 3: $O(1)$ layer for



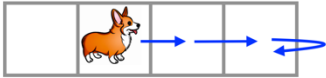
- Parallel boundary detector:

- Compute prefix sums  $z_t := \sum \sigma_{1:t}$  (ignoring boundaries);
- At each  $t$ , find most recent  $t_{\text{uniq}} < t$  such that  $z_{t_{\text{uniq}}:t}$  has  $n(\text{\#states})$  unique values;
- Then  $t_{\text{final}} := \max_{t_{\text{uniq}} \leq \tau \leq t} (\text{argmax } z_\tau, \text{argmin } z_\tau)$  is last boundary collision.



# Takeaways

For any length  $T$ , Transformers can simulate  $\mathcal{A}$  with  $o(T)$  depth.

- Theorem 1:  $O(\log T)$ -layer simulation for *all*  $\mathcal{A}$ 
  - Parallel prefix computation (divide and conquer); lower bound for general  $\mathcal{A}$ .
- Theorem 2:  $O(|Q|^2 \log |Q|)$ -layer simulation for all *solvable*  $\mathcal{A}$ 
  - Factorization (Krohn-Rhodes).
- Theorem 3:  $O(1)$ -layer simulation for *gridworld* 
  - Specific  $\mathcal{A}$  : even shallower results (e.g. via parallel boundary detector).

# Empirical findings

Positive results, challenges

# Overview

$$\sigma_{1:T} \rightarrow \text{Transformer} \rightarrow q_{1:T}$$

## *(Theory)*

- Q0: are shallow non-recurrent nets sufficiently expressive? [Yes!]

## *(Experiments)*

- Q1: Can SGD find shortcuts in practice?
- Q2: Shortcomings of shortcuts?
  - Q2.1: Does SGD work with limited supervision?
  - Q2.2: Are shortcuts robust to unseen inputs?
- Q3: Solutions?

## *(Open question)*

- Q4: How to interpret the shortcuts?
- Q5: How to design an architecture to *solve* reasoning tasks?



# SGD works, under ideal supervision

|           | Transformer depth           |      |      |      |      |      |      |      |      |      |      |      |      |      |      |      |
|-----------|-----------------------------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
|           | 1                           | 2    | 3    | 4    | 5    | 6    | 7    | 8    | 9    | 10   | 11   | 12   | 13   | 14   | 15   | 16   |
| automaton | Dyck                        | 99.3 | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  |
|           | Grid <sub>4</sub>           | 99.9 | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  |
|           | Grid <sub>9</sub>           | 92.2 | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  |
|           | C <sub>2</sub>              | 77.6 | 99.8 | 99.9 | 100  | 100  | 99.5 | 100  | 99.7 | 100  | 100  | 100  | 100  | 100  | 100  | 100  |
|           | C <sub>3</sub>              | 54.6 | 94.6 | 96.7 | 99.4 | 100  | 100  | 99.8 | 100  | 99.9 | 100  | 100  | 100  | 100  | 99.8 | 100  |
|           | C <sub>4</sub>              | 95.1 | 92.3 | 84.2 | 99.9 | 99.7 | 99.9 | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  |
|           | C <sub>5</sub>              | 89.0 | 99.1 | 99.9 | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  |
|           | C <sub>6</sub>              | 59.8 | 98.7 | 75.5 | 99.9 | 99.8 | 99.9 | 99.9 | 100  | 100  | 100  | 99.8 | 99.9 | 100  | 99.8 | 99.9 |
|           | C <sub>7</sub>              | 90.9 | 95.0 | 99.9 | 99.9 | 100  | 99.9 | 100  | 100  | 100  | 100  | 99.8 | 100  | 100  | 100  | 100  |
|           | C <sub>8</sub>              | 79.6 | 96.2 | 99.8 | 99.8 | 99.9 | 100  | 99.9 | 99.9 | 100  | 99.4 | 99.9 | 99.9 | 100  | 99.9 | 99.9 |
|           | C <sub>2</sub> <sup>2</sup> | 90.5 | 98.8 | 99.9 | 100  | 100  | 99.9 | 100  | 100  | 99.9 | 100  | 100  | 100  | 100  | 100  | 100  |
|           | C <sub>3</sub> <sup>2</sup> | 65.0 | 77.9 | 99.9 | 97.9 | 100  | 99.8 | 98.2 | 99.9 | 100  | 100  | 91.9 | 95.9 | 91.7 | 90.6 | 87.5 |
|           | D <sub>6</sub>              | 25.4 | 27.2 | 47.4 | 75.2 | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  |
|           | D <sub>8</sub>              | 45.6 | 98.0 | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  |
|           | Q <sub>8</sub>              | 31.6 | 49.2 | 59.6 | 60.4 | 73.5 | 99.3 | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  |
|           | A <sub>4</sub>              | 25.0 | 35.4 | 49.1 | 59.3 | 62.6 | 82.3 | 90.9 | 98.0 | 98.0 | 99.1 | 99.8 | 100  | 99.7 | 100  | 100  |
|           | A <sub>5</sub>              | 12.5 | 23.1 | 32.5 | 46.7 | 71.2 | 98.8 | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  | 100  |
|           | S <sub>4</sub>              | 11.3 | 17.6 | 22.0 | 27.1 | 37.7 | 44.8 | 50.8 | 72.5 | 91.3 | 97.1 | 97.9 | 98.7 | 99.9 | 100  | 99.8 |
|           | S <sub>5</sub>              | 7.9  | 11.8 | 14.6 | 19.7 | 26.0 | 28.4 | 32.8 | 51.8 | 86.3 | 94.8 | 90.2 | 97.2 | 99.3 | 99.1 | 99.9 |

Q1: Does SGD on Transformers find shortcuts? *Yes!*

**Group-free semiautomata** (reset): Dyck, gridworld

- Easy to learn; generalizes Dyck results [Yao et al. '22]

**Cyclic groups** (mod- $n$  counters): unstable training & o.o.d. eval

- possibly accounts for previous negative results [Bhattamishra et al. '20]
- **open challenge**: improve architectures and training.

**Other abelian groups**: worse instabilities; higher depth helps training

**Harder groups**: more results including  $D_8$ ,  $A_5$  (non-solvable),  $S_5$  ( $NC^1$ -complete).

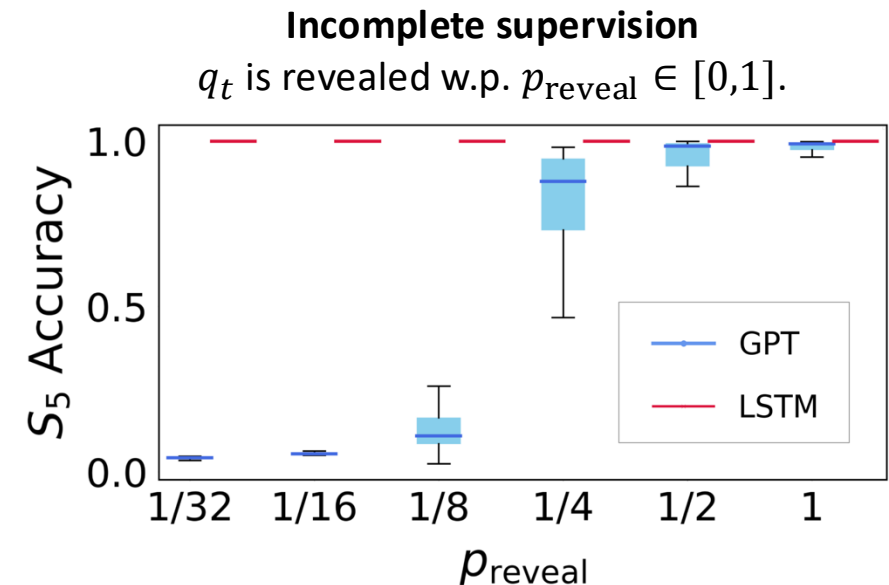
- Groups with deeper factorization requires mores layers
- **open challenge 1**: dissect/interpret the learned solutions
- **open challenge 2**: precisely characterize instance complexity

# Training robustness: SGD beyond ideal supervision

Q2.1: Does SGD work under limited supervision? *Up to a point.*

- *Setup*: reduce the amount of state info during training; in-distribution eval.

| Indirect supervision<br>train & test on a function of $q_t$ . |                                |                |                          |          |
|---|--------------------------------|----------------|--------------------------|----------|
| Dyck <sub>4,8</sub>   | Grid <sub>9</sub>              | $S_5$          | $C_4$                    | $D_8$    |
| stack top   | $\mathbb{1}_{\text{boundary}}$ | $\pi_{1:t}(1)$ | $\mathbb{1}_{0 \bmod 4}$ | location |
| 100.0   | 99.8                           | 99.8           | 99.7                     | 99.8     |

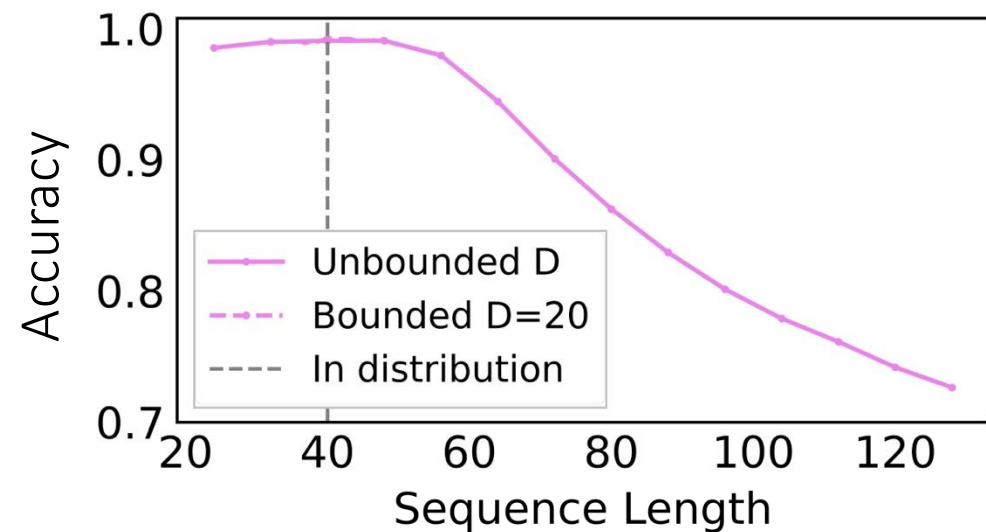
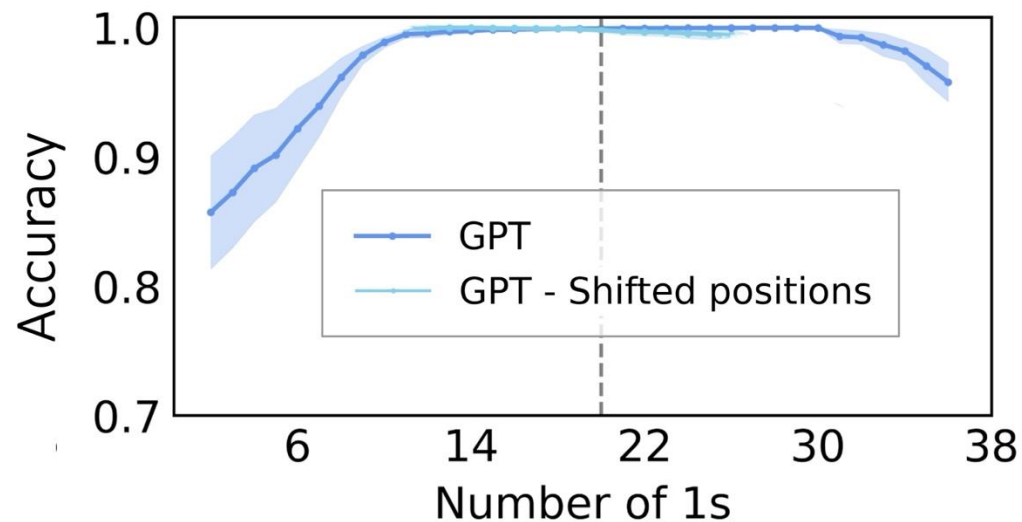


**Takeaway:** learning is still possible, but not as robust as RNNs (LSTM always 100%).

# Testing robustness: hallucinated variables

Q2.2: Are shortcuts robust to unseen inputs? **No.**

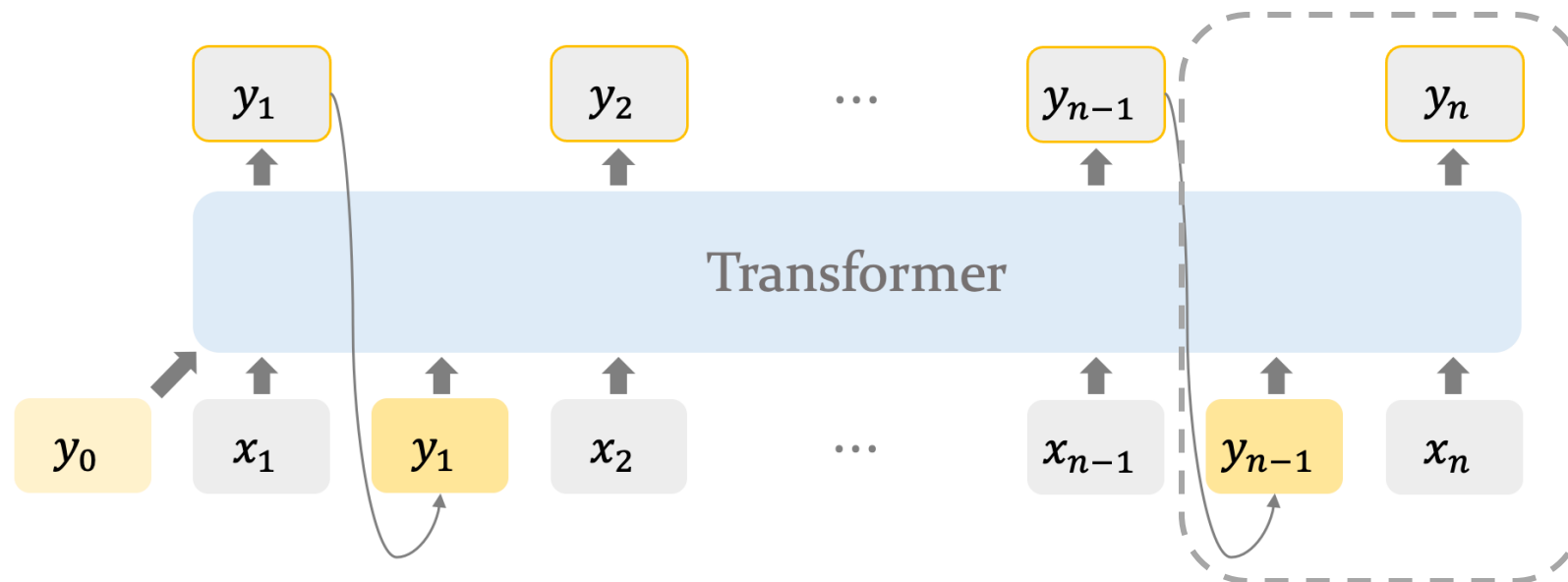
- **Parity** ( $C_2$ ): ideal training with  $p(1) = 0.5$ , evaluate under distribution shifts.
  - Shortcut  $q_t = (\sum_{i \in [t]} \sigma_i) \bmod 2 \rightarrow (\sum_{i \in [t]} \sigma_i) \approx t/2$  with deviation  $\sim \sqrt{t}$ .
  - **mod 2** is **memorized** by MLP: fail to generalize to diff  $(\sum_{i \in [t]} \sigma_i)$ .
- Transformer solutions? Same failure mode  $\rightarrow$  maybe same solution.



# The recurrent mode of Transformers

Q3: Solutions? Guiding Transformers to learn recurrent solutions.

- *Setup*: train with previous states as inputs;



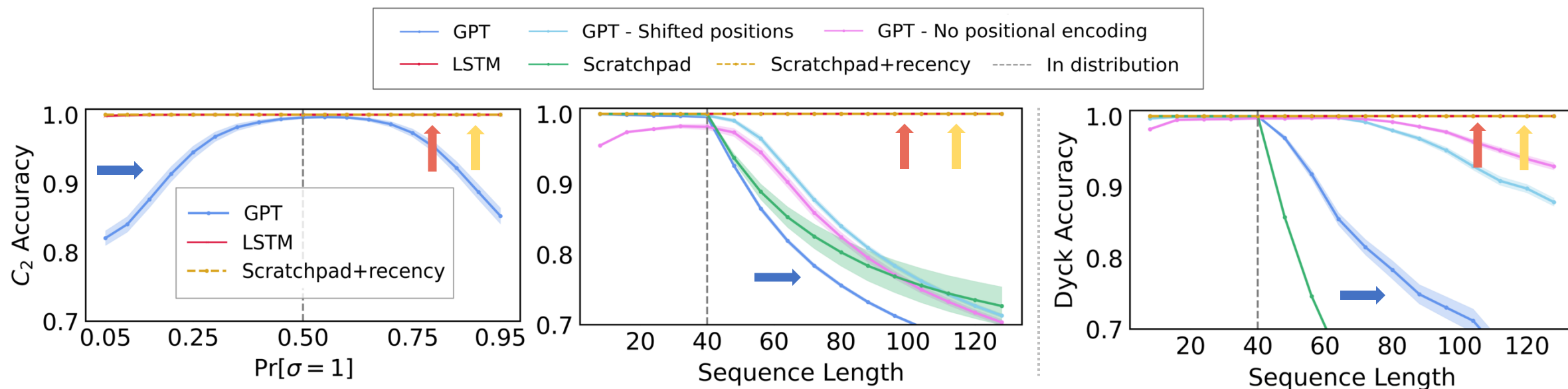
Scratchpad (Nye et al. 21)  
(input  $x_t = \sigma_t$ , output  $y_t = q_t$ )

$$q_t = \delta(q_{t-1}, \sigma_t)$$

# The recurrent mode of Transformers

Q3: Solutions? Guiding Transformers to learn recurrent solutions.

- *Setup*: train with previous states as inputs; eval at diff distributions or lengths.



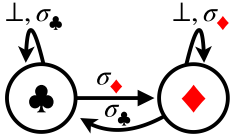
*Takeaway*: Transformers turned recurrent with **scratchpad** [Nye et al. 22] + **recency bias** [Press et al. 21] → Open: *Can we learn shortcuts that generalize?*

# Takeaway

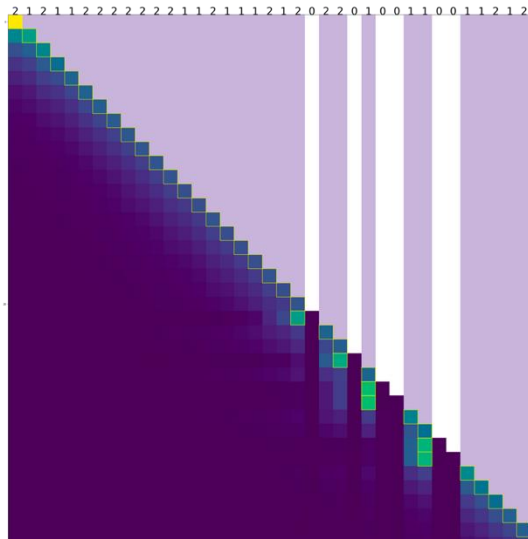
- **Positive**: Transformers with SGD can find good in-distribution solutions.
  - The trend roughly matches our beliefs on the difficulty of the tasks.
- **Challenges**: shortcuts are **less robust** than recurrent methods
  - Struggle at OOD generalization / changes in training setups.
    - Open question: How to thoroughly test for generalization?
  - Fix: made recurrent by scratchpad + recency bias.
- **Mechanistic understanding**
  - Gridworld: boundary detection.
  - Parity: evidence for implementing  $(\sum_t \sigma_t) \bmod 2$ .

# Discussions: Interpretability and generalization

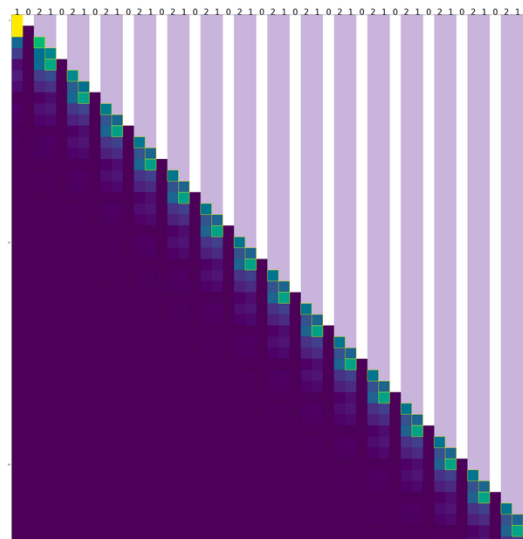
*How to test for generalization?*  $\infty$  unseen inputs -- how much do we need to probe?

e.g. Flipflop  : train with  $p(0) = 0.5, p(1) = p(2) = \frac{1-p(0)}{2}$ .

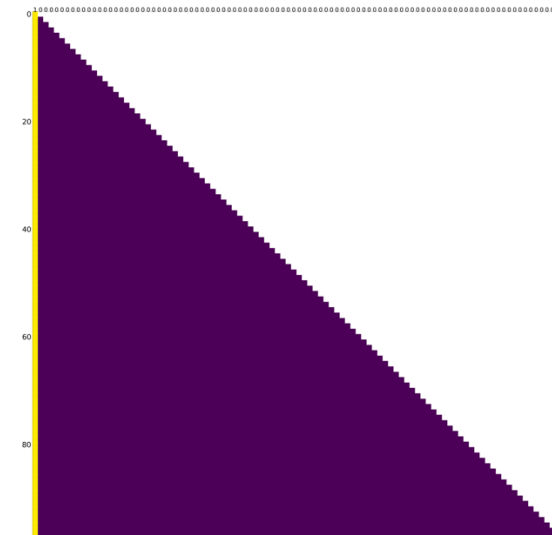
- Test:  $p(0) \in \{0.1, 0.2, \dots, 0.9\} \times (100\text{k len-100 seqs})$ : 100% accuracy



random with small  $p(0)$



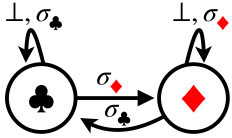
$[1,0,2] \cdot n$



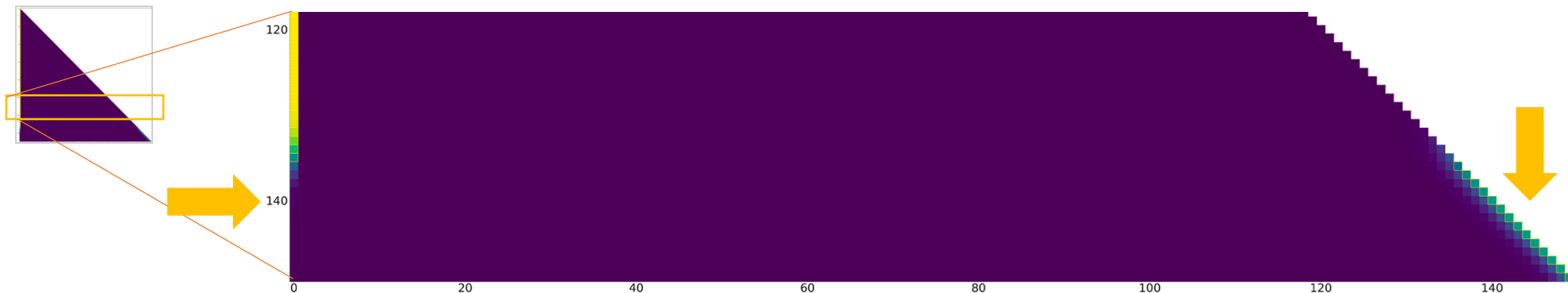
$[1,0,0, \dots]$

# Discussions: Interpretability and generalization

*How to test for generalization?*  $\infty$  unseen inputs -- how much do we need to probe?

e.g. Flipflop  : train with  $p(0) = 0.5, p(1) = p(2) = \frac{1-p(0)}{2}$ .

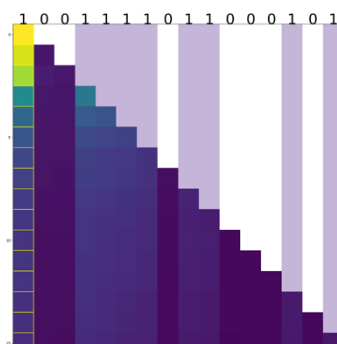
- Test: 100% for  $p(0) \in \{0.1, 0.2, \dots, 0.9\}$ , for 100k len-100 seqs per  $p(0)$ .
- $[1, 0, 0, 0, \dots, 0]$  is the hardest sample -- long-term dependency solved! 😊
- Not quite: failing on length generalization. 😞



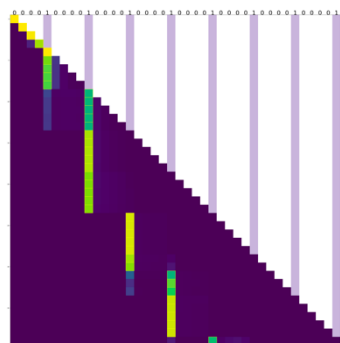


# Discussions: (mechanistic) interpretability

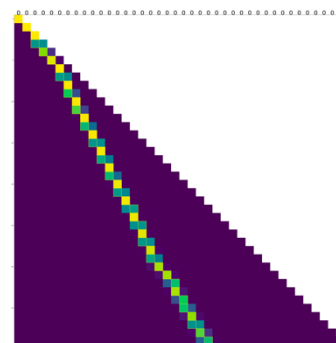
- Parity: what if not “sensible”? Variance (across randomness) in the patterns?



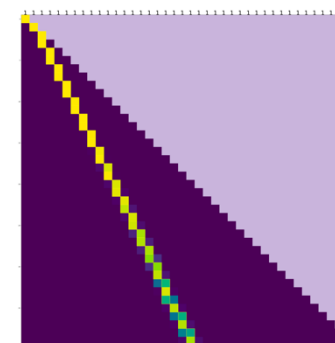
attend to 1s only



[0,0,0,1]\*10

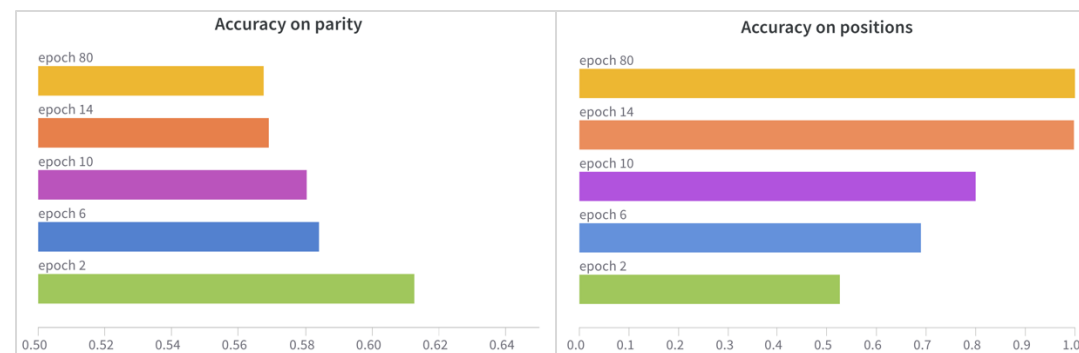
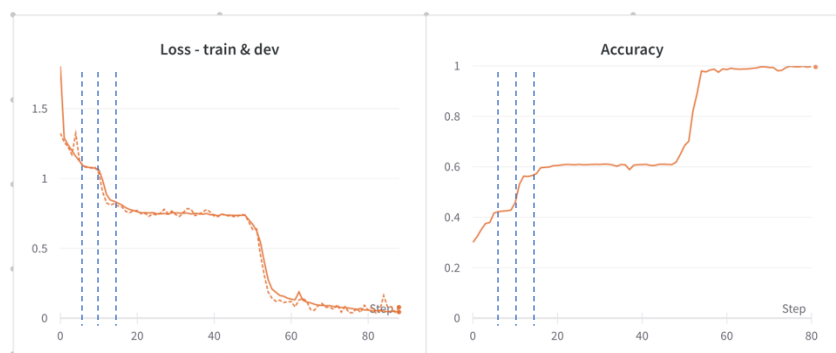


all-0s



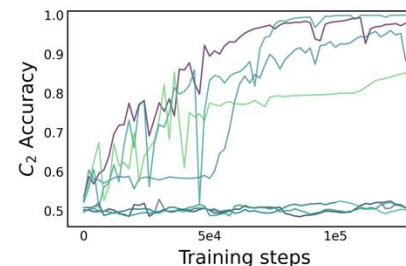
all-1s

- Dihedral group  : not learning the parity (on direction).



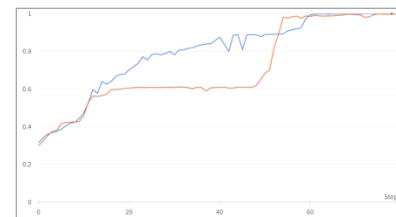
# Discussions: optimization

- Improve / stabilize training?
  - e.g. Parity: without positional encoding? With 1 layer?

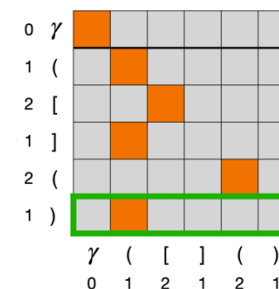


- How to find (hidden) progress measures?

- [Barak 22](#), [Nanda 23](#)



- What solutions are preferred, e.g. among shortcuts?
  - Dyck: sparse in theory ([Yao 20](#)), uniform in practice.
  - Are some solutions *better* than others?



- Modified architecture: parity: no issue with **mod** if using  $\sin(\sum \sigma_t)$ .
  - How to optimize with sinusoidal activation?

# Discussions

- **Generalization**
  - Is it possible to have *guarantees* via tests (e.g. a “complete” test set)?
  - Is interpretability required for true generalization?
- **Synthetic & real**
  - *Why synthetic*: clean setup + cheaper + infinite supply of data
    - Decomposition → understand basic units first
    - Easier to formalize & understand & diagnose & fix
  - *Why not synthetic*: not directly useful
    - What’s missing: factual aspects? “Complex” structures?
  - *Goal*: Transfer insights to code / math / languages.
- **Shortcut & recurrent**: best of both worlds? ([RWKV](#)?)

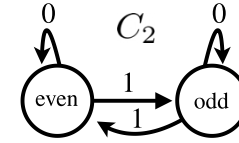
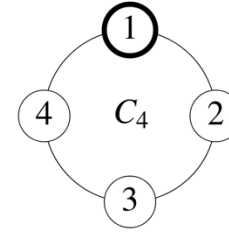
# Transformers Learn Shortcuts to Automata

TL;DR:  $o(T)$ -depth Transformers can simulate  $\mathcal{A}$ , in theory and practice

- **Theory:** for any length  $T$ , Transformers can learn:
  - $O(\log T)$ -layer for *all*  $\mathcal{A}$  – parallel prefix computation
    - Non-solvable  $\mathcal{A}$ : matching lower bound (Barrington)
  - $O(|Q|^2 \log |Q|)$ -layer for all *solvable*  $\mathcal{A}$  – factorization with Krohn-Rhodes
  - $O(1)$ -layer for *gridworld* – boundary detector
- **Empirical study:** shortcuts can be found but are *brittle* OOD.
  - Fix: make Transformers recurrent (scratchpad + recency bias).
- **Future work:** understanding and improving the model?

# Appendix

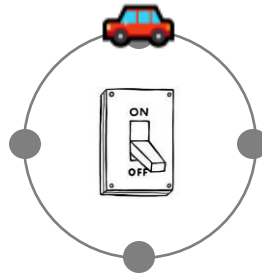
# Theorem 2: the glue



Direct product  $\times$ , e.g. 🦓  $C_4 \times C_2$

Two *independent* groups

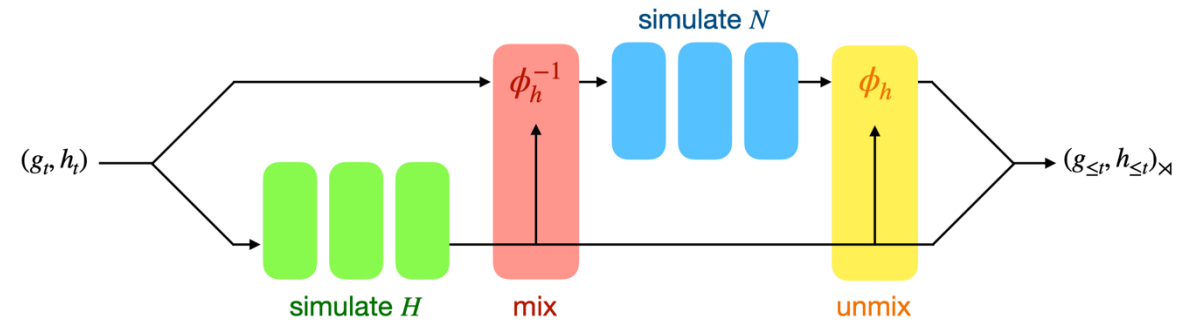
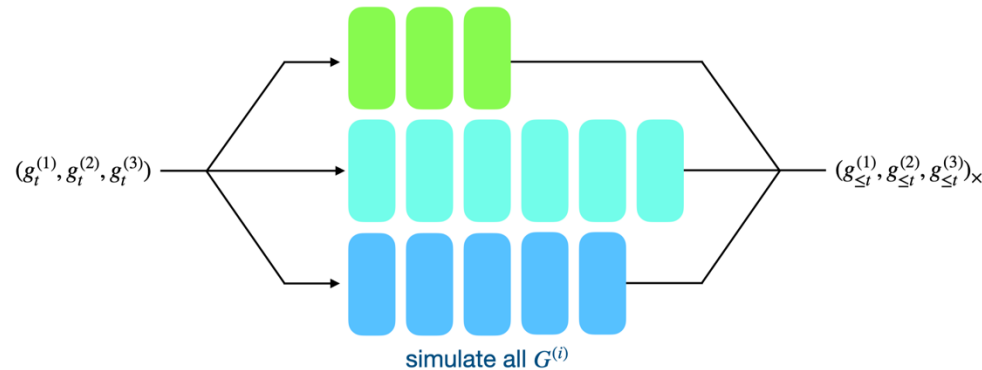
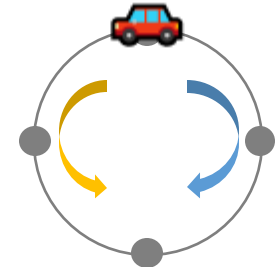
- $(g_1, h_1) \cdot (g_2, h_2) = (g_1 g_2, h_1 h_2)$
- e.g. car + a light switch



Semidirect product  $\rtimes$ , e.g. 🦀  $D_8 \cong C_4 \rtimes C_2$

Two *interacting* groups

- $(g_1, h_1) \cdot (g_2, h_2) = (g_1 h_2 g_2 h_2^{-1}, h_1 h_2)$
- e.g. car + direction toggle

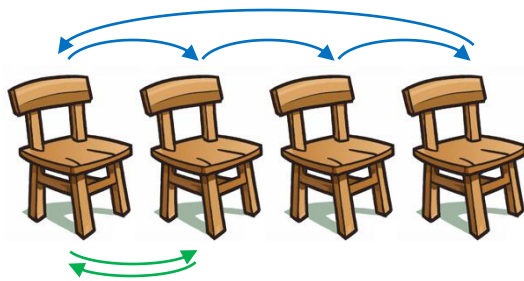


# What about *semigroups*?

$$\mathcal{T}(\mathcal{A}) := \{\delta(\cdot, \sigma) : \sigma \in \Sigma\} \text{ under composition}$$

More complicated: **rank collapses**.

**$n$ -player musical chairs**



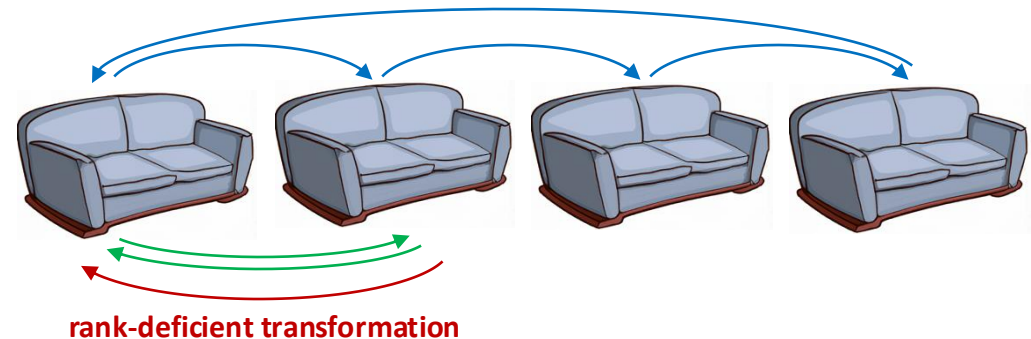
$Q = \{\text{positions of } n \text{ players}\}$

$\Sigma = \{ \text{cycle, swap} \}$

$$\begin{bmatrix} 1 & & & 1 \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix} \quad \begin{bmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix}$$

$\mathcal{T}(\mathcal{A}) = S_n$ : all  **$n!$**  permutations on  $[n]$

**$n$ -player musical sofas**



$Q = \{\text{positions of } n \text{ players}\}$

$\Sigma = \{ \text{cycle, swap, merge} \}$

$$\begin{bmatrix} 1 & & & 1 \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix} \quad \begin{bmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix} \quad \begin{bmatrix} 1 & 1 & & \\ & & & \\ & & 1 & \\ & & & 1 \end{bmatrix}$$

$\mathcal{T}(\mathcal{A}) = T_n$ : all  **$n^n$**  functions  $[n] \rightarrow [n]$

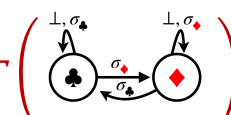
# Prime factorizations of algebraic objects

- Universal structure theorems in abstract algebra:
  - Integers:  $N = p_1 \cdot p_2 \cdots p_n$ , prime numbers  $p_i$  [Euclid ~300 BC]
  - Groups:  $G \triangleright H_n \triangleright \cdots \triangleright H_1$ , simple groups  $H_{i+1}/H_i$  [Jordan & Hölder ~1880]
  - Semigroups: *do we know anything if we're only given associativity?*
- Yes! [Krohn & Rhodes '65]

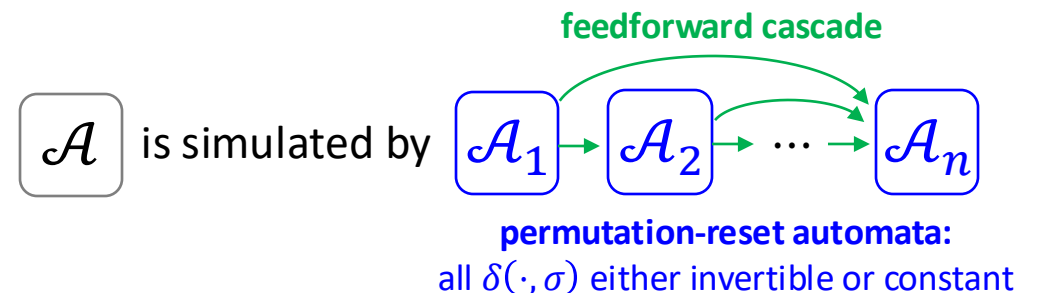
## Krohn-Rhodes theorem (semigroups)

$$G \leq \underbrace{H_n}_{\text{simple groups}} \wr \underbrace{M}_{\text{flip-flop monoid } \mathcal{T}} \cdots \wr \underbrace{H_2}_{\text{simple groups}} \wr \underbrace{M}_{\text{flip-flop monoid } \mathcal{T}} \wr H_1$$

wreath product



## Krohn-Rhodes theorem (semiautomata)










# Factorization: from integers to groups

$$8 = 2 \times 2 \times 2$$

- Why groups get complicated: **combinatorial explosion**

|   |   |                             |
|---|---|-----------------------------|
|  | $C_8$ : mod-8 addition  |                             |
|  | $E_8 \cong C_2 \times C_2 \times C_2$ : 3-bit vectors under XOR |                             |
|  | $C_4 \times C_2$ : non-interacting mod-4 & parity               |                             |
|  | $D_8 \cong C_4 \rtimes C_2$ : rotations/reflections of a square | } non-abelian: $gh \neq hg$ |
|  | $Q_8$ : multiplication of unit quaternions                      |                             |

- Finite group theory**: classical toolbox for understanding symmetries

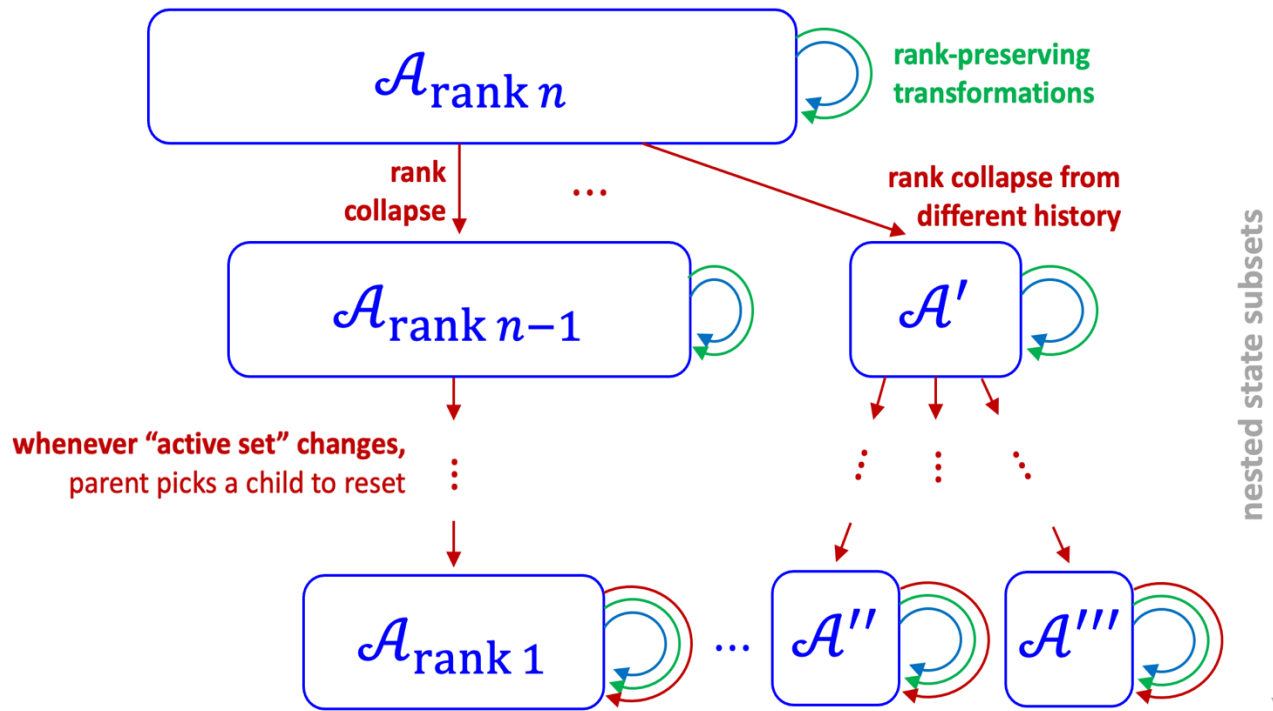
$$C_8, E_8, C_4 \times C_2, D_8, Q_8 \leq (C_2 \wr C_2) \wr C_2$$

**Jordan-Hölder factors** (simple groups)

**Krasner-Kaloujnine embedding** (wreath product)

# Krohn-Rhodes intuitions

Tracking rank collapses (*holonomy decomposition*)

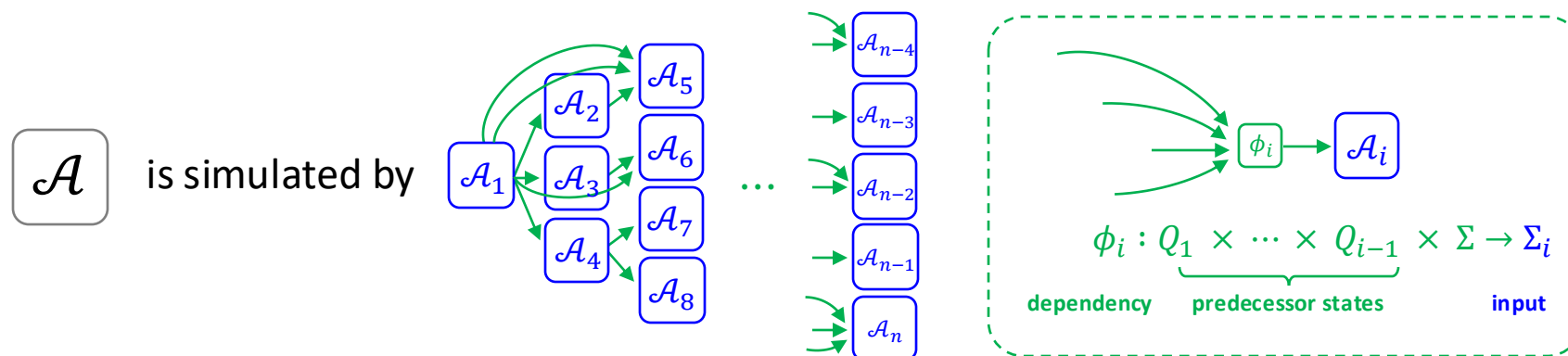


Number of layers:

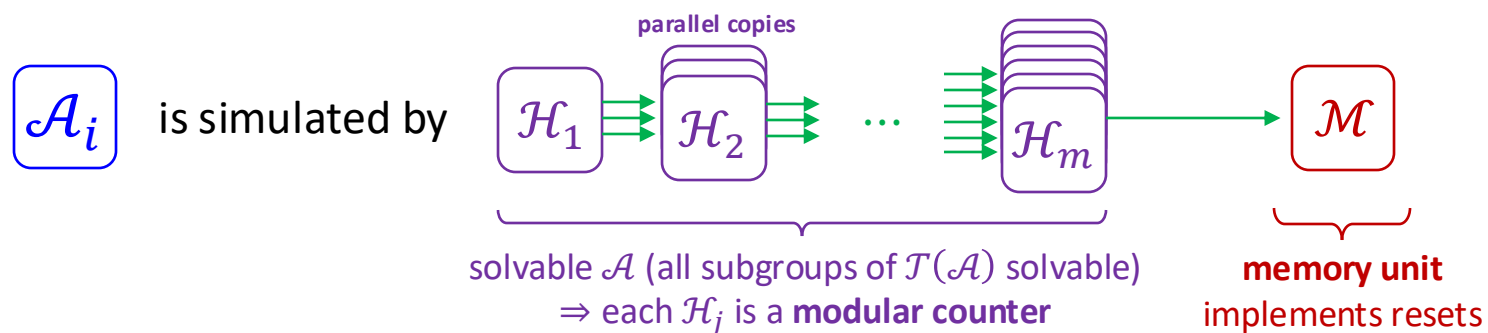
- Solvable groups:  $O(\log |G|)$ 
  - mod counter
- Permutation-reset semiautomaton:  $O(\log |G|) + 2 \leq O(|Q| \log |Q|)$ .
  - mod counter + memory unit
- Semiautomaton:  $\leq |Q|$  levels of the above.

# Proof of Krohn-Rhodes: key intuitions

- Holonomy decomposition “compiles” to a cascade



- Permutation-reset semiautomata factorize further

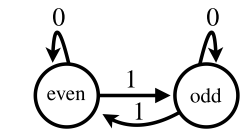


group theory under the hood:  
 $\mathcal{T}(\mathcal{H}_j)$  are simple groups from  
 Jordan-Hölder composition factors,  
 which are all cyclic if  $\mathcal{A}$  is solvable

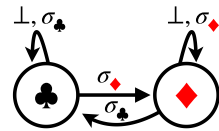
realized by **universal embedding theorem**  
 [Krasner & Kaloujnine '51]

# Implications for simulating automata

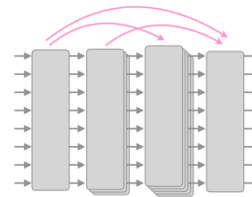
- Krohn-Rhodes: *all*  $\mathcal{A}$  decompose into permutation-reset  $\{\mathcal{A}_i\}$
- Jordan-Hölder: *all*  $\mathcal{A}_i$  decompose into simple group machines  $\{\mathcal{H}_i\}$
- Recall: *when can we find a solution like  $\Sigma \sigma_{1:t} \bmod 2$  for parity?*
- Answer: whenever the “*atoms*” and “*glue*” are implementable



mod- $n$  counter



$n$ -state memory unit



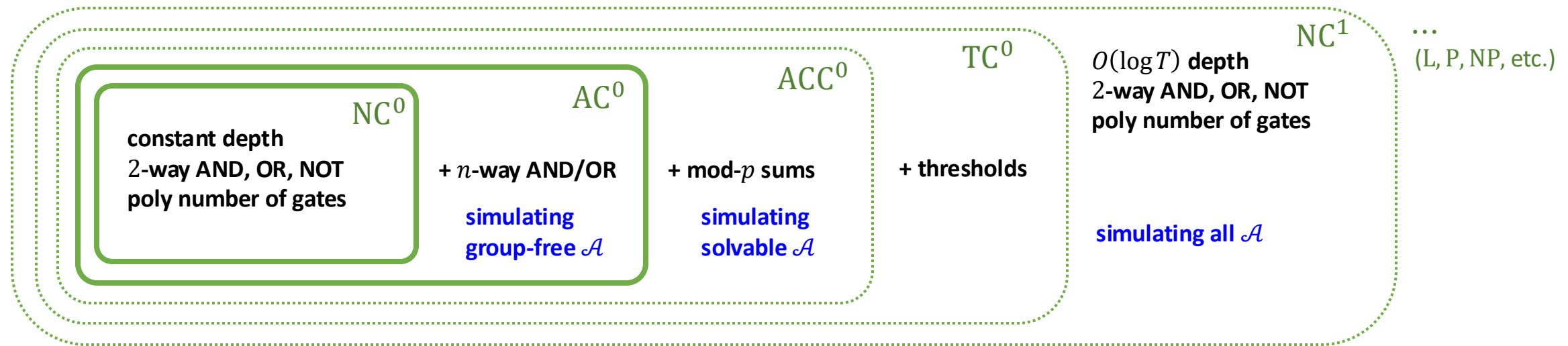
transformation cascade

sufficient when all groups  
within  $\mathcal{T}(\mathcal{A})$  are **solvable**

- Need circuit complexity to formalize the question...

# Quantifying efficient parallel circuits

- **Goal:** formalize “Krohn-Rhodes implies efficient simulation”
- Low-depth parallel algorithms are best captured by **circuit complexity**

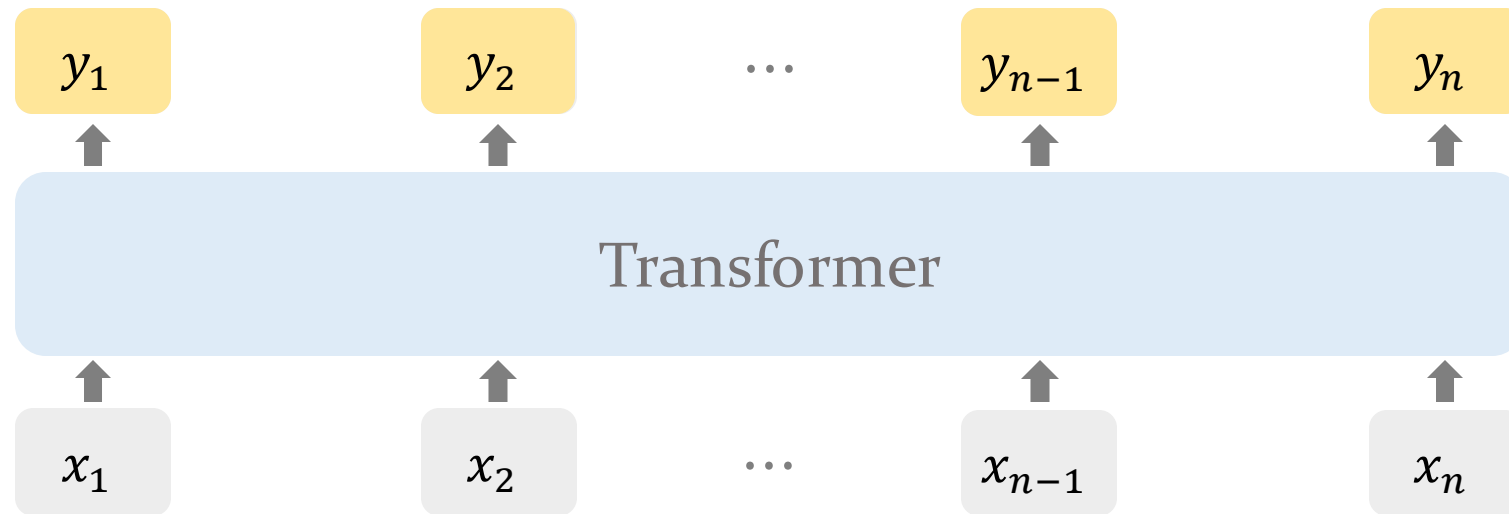


Embarrassingly open: are any of the ☐ proper?  $\text{ACC}^0 \stackrel{?}{=} \text{NP}$  ?



# Scratchpads (modification of Nye et al. 21)

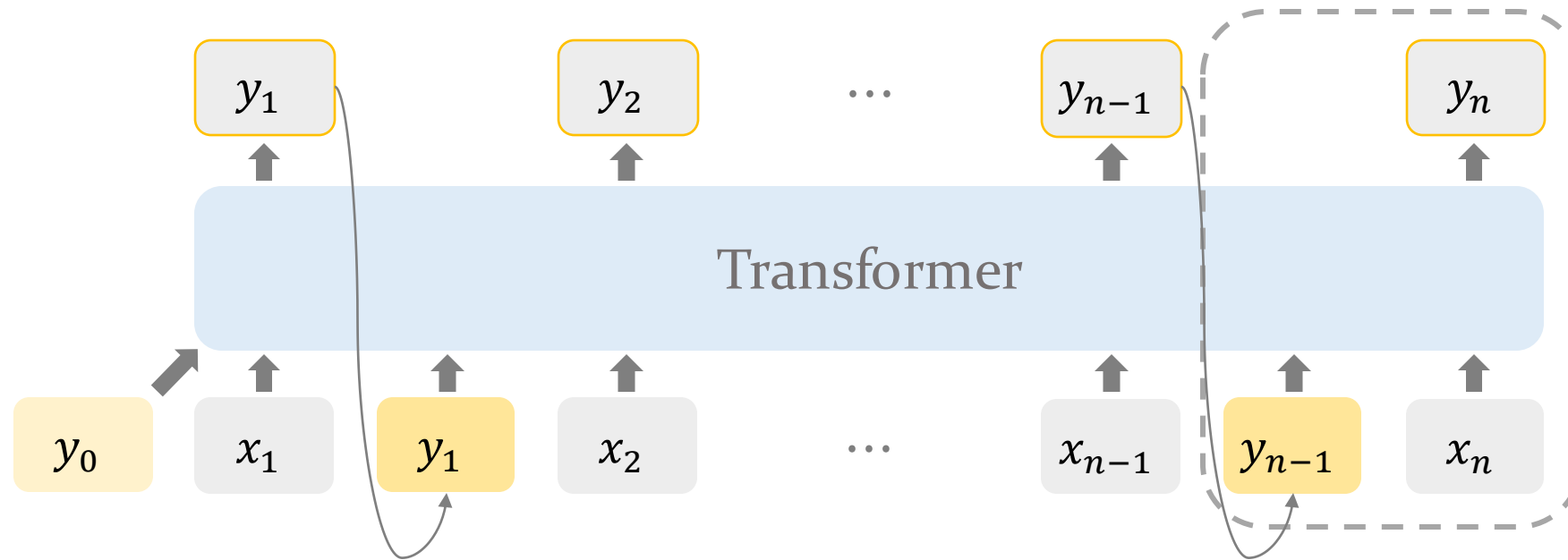
Idea: make the model **recurrent** with scratchpad (~buffer): explicitly modeling states.



$$\text{want: } y_i = x_i \oplus y_{i-1}$$

# Scratchpads (modification of Nye et al. 21)

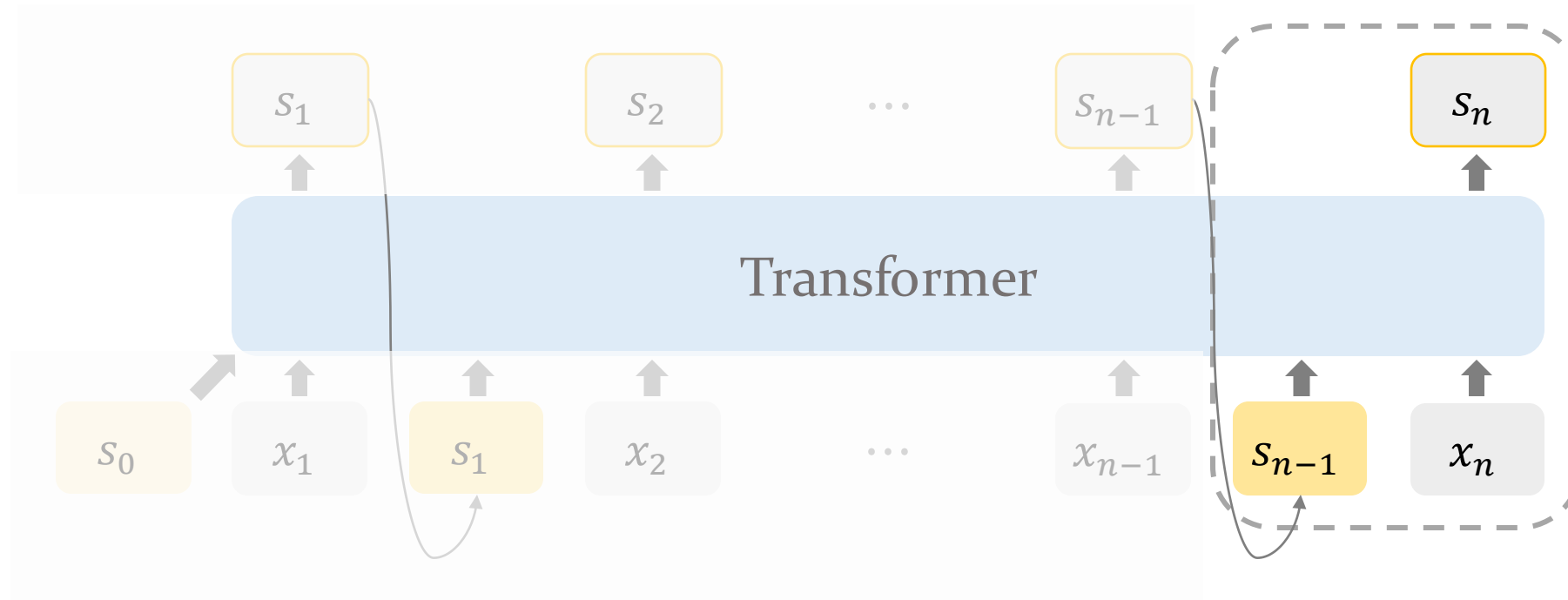
Idea: make the model recurrent with **scratchpad** (~buffer): explicitly modeling states



$$\text{want: } y_i = x_i \oplus y_{i-1}$$

# Scratchpads (modification of Nye et al. 21)

Idea: make the model recurrent with **scratchpad** (~buffer): explicitly modeling states



want:  $s_i := y_i = x_i \oplus s_{i-1}$