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NEURAL INFORMATION  
PROCESSING SYSTEMS

**Carnegie  
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# Thinking Fast with Transformers

Algorithmic Reasoning with Shortcuts



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UPenn

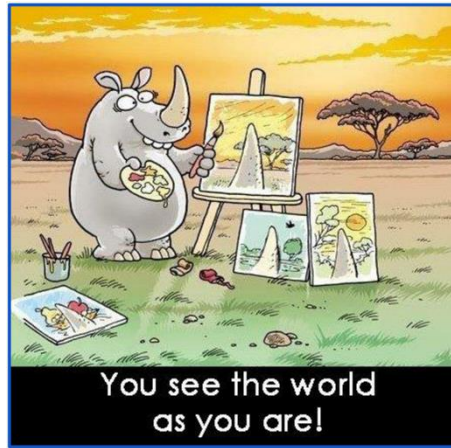
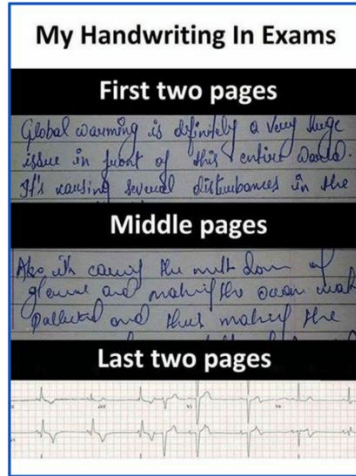


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MSR NYC



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MSR NYC

# Reasoning in language models



😊 Powerful and practically useful.

*Capabilities and limitations?*



Yes, I can help you with binary addition! Binary numbers use base 2, which means there are only two digits: 0 and 1. To add

:



So, the final result is:

Copy code

111013011

3?



Unreliable with incorrect answers.

# Agenda

Q: How can *parallel* models such as Transformers model *sequential* reasoning?

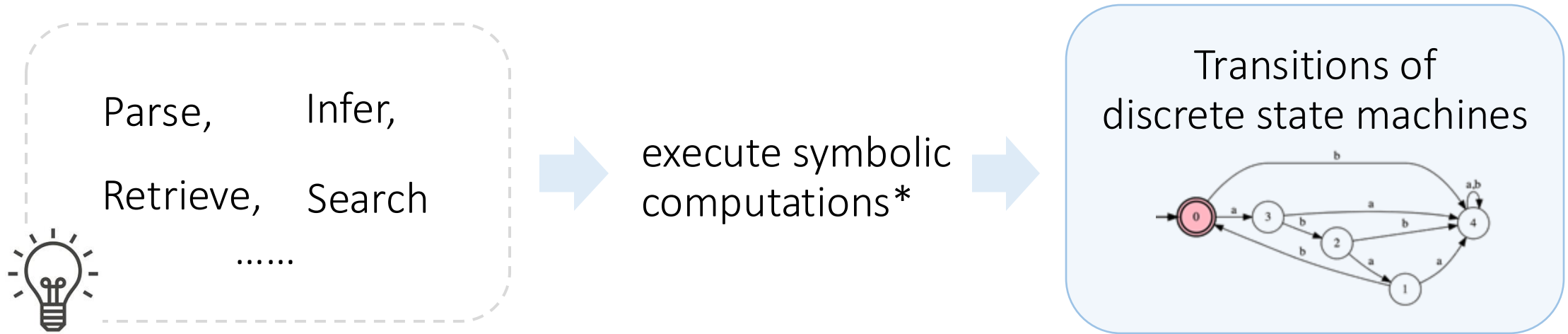
Formalizing with **automata**:



- Capabilities in theory (representational)
- Solutions found in practice (optimization, generalization)

**TL;DR:** Transformers reason with **shallow solutions**, with computational advantages but statistical issues.

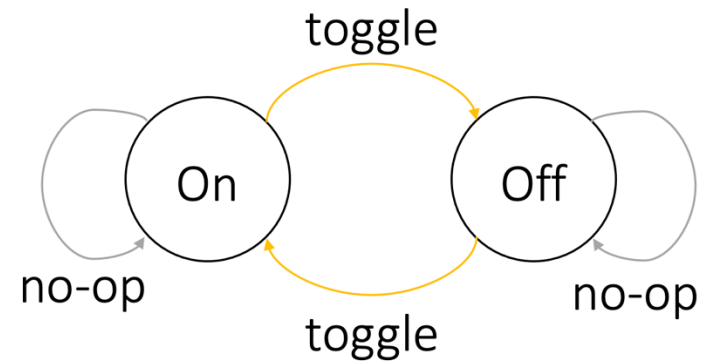
# Formalizing reasoning



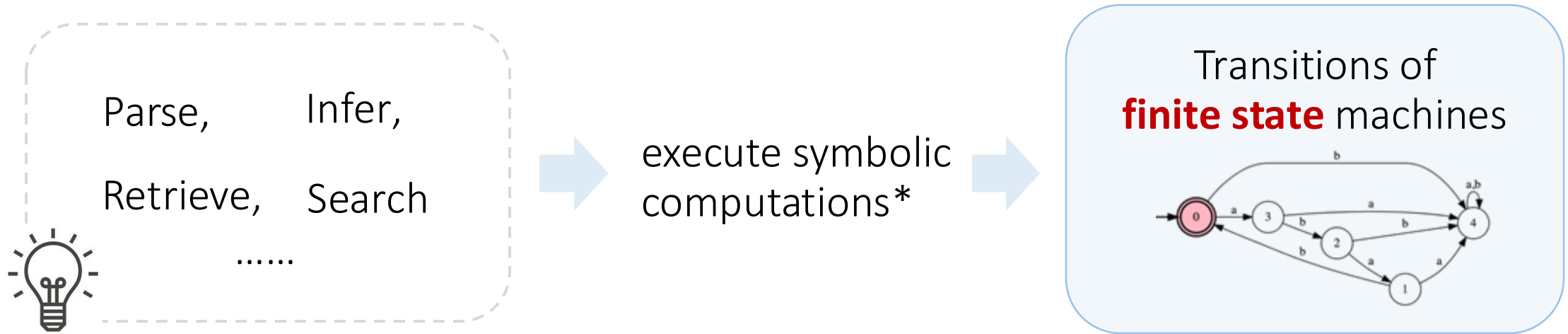
## parity

An **on-off** switch is off.  
(actions: **toggle** or **not**)  
Now the switch is ?.

[Han 20, Anil et al. 22]



# Formalizing reasoning



An on-off switch is off.  
(actions: toggle or not)  
Now the switch is ?.

Parity

[Han 20, Anil et al. 22]

```
00010011
+ 10100110
-----
10111001
```

Addition

[Nogueira et al. 21]

example@cmu.edu

@([a-zA-Z0-9\_+-.]+)\.[a-zA-Z0-9\_+-.]

Regular expressions

[Bhattamishra et al. 20]

```
12 <div>
13 <div>
14 <div>
15 <ul>
16 <li></li>
17 <li></li>
18 <li></li>
19 <li></li>
20 </ul>
21 </div>
22 </div>
23 </div>
```

Bounded nested brackets

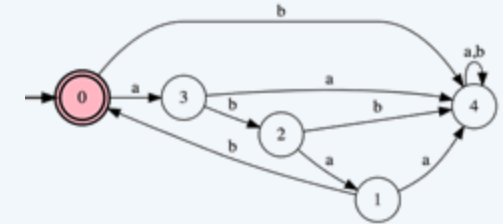
[Yao et al. 21]

# Formalizing reasoning

*Wide ranges of reasoning tasks*

finite-state automata ↔ regular languages

Transitions of  
**finite state** machines



An on-off switch is off.  
(actions: toggle or not)  
Now the switch is ?.

Parity

[Han 20, Anil et al. 22]

```
00010011
+ 10100110
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Addition

[Nogueira et al. 21]

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[Bhattamishra et al. 20]

```
12 <div>
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20       </ul>
21     </div>
22   </div>
23 </div>
```

Bounded nested brackets

[Yao et al. 21]

# Formalizing reasoning with automata

$$\mathcal{A} = (Q, \Sigma, \delta)$$

states      inputs      transitions

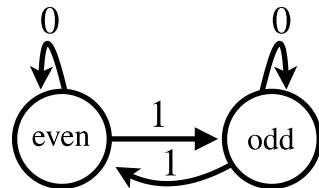
$$q_t = \delta(q_{t-1}, \sigma_t)$$

( $Q$  is finite)

parity counter

$Q = \{\text{even}, \text{odd}\}$

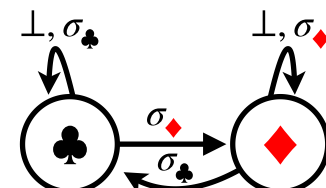
$\Sigma = \{0, 1\}$



1-bit memory unit

$Q = \{\clubsuit, \diamondsuit\}$

$\Sigma = \{\sigma_{\clubsuit}, \sigma_{\diamondsuit}, \perp\}$   
(no-op)



*(will reappear later)*

*Task:* modeling the dynamics of  $\mathcal{A}$ .

# Task: Simulating automata

$$\mathcal{A} = (Q, \Sigma, \delta)$$

states, inputs, transitions

Simulating  $\mathcal{A}$ : learn a *seq2seq function* for sequence length  $T$ .

- Input =  $\sigma_1, \sigma_2, \dots, \sigma_T \in \Sigma$  (alphabet), output =  $q_1, q_2, \dots, q_T \in Q$  (states).

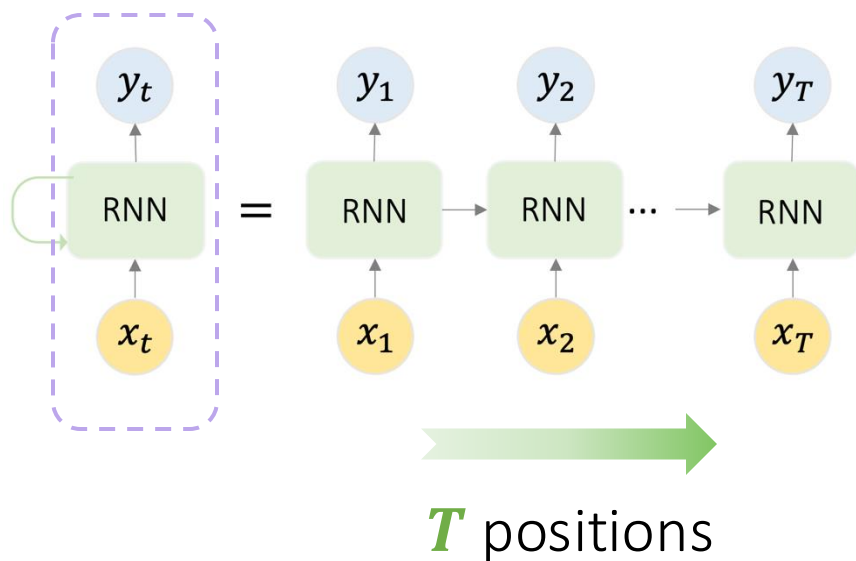


# Architecture choices

## RNN

**sequential** across positions

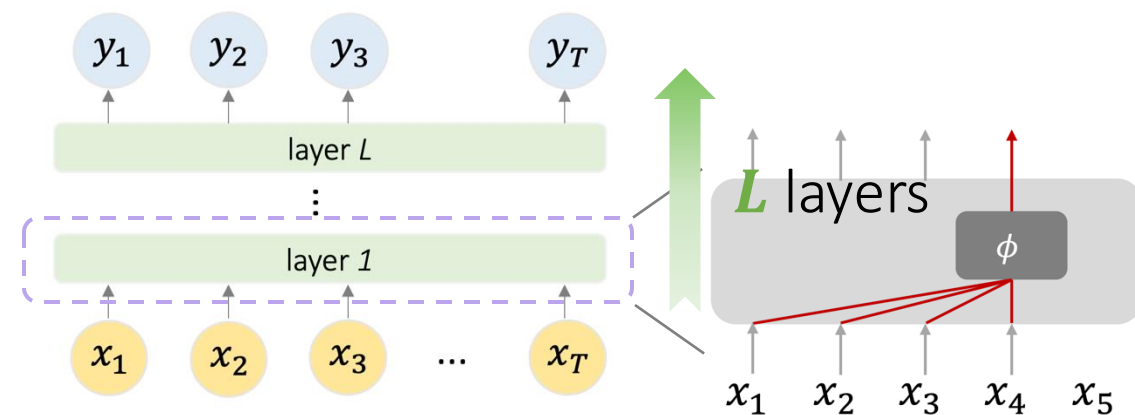
Natural for  $q_t = \delta(q_{t-1}, \sigma_t)$



## Transformer

**parallel** across positions

sequential across layers



Typically  $L \ll T$ .

# Task: Simulating automata

$$\mathcal{A} = (Q, \Sigma, \delta)$$

states, inputs, transitions

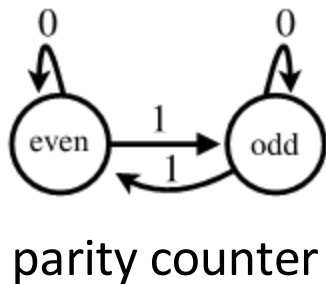
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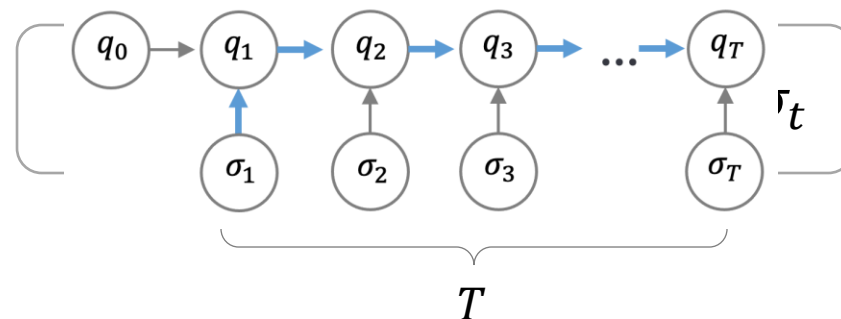
Note: more than 1 way to simulate  $\mathcal{A}$ .

Shortcut

$o(T)$  # sequential steps



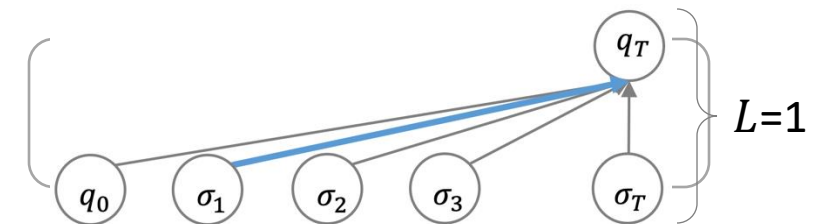
Iterative solution



“RNN solutions”

✗ Not shortcut

Parallel solution



“Transformer solutions”

✓ Shortcut

# Transformers learn shortcut to automata

*Q: How **parallel** models such as Transformers perform **sequential** reasoning?*

**Theoretically:** **shortcut** solutions

- How short can the shortcuts be?
  - Measured by network depth.
- What structure/properties are needed?
  - Tools: group theory, Krohn-Rhodes.

**Empirically:**

- Can shortcuts be found?
  - Is theory predictive?
- What are the empirical solutions?
  - Same as the constructions?
  - Properties?

# Solutions of Reasoning

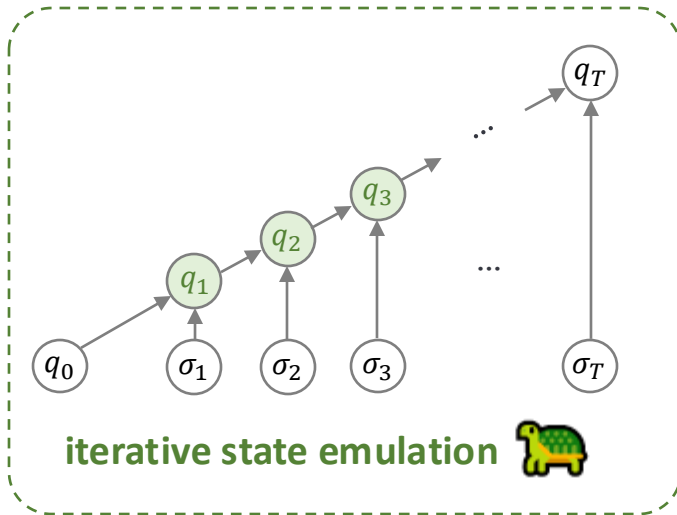


$$\mathcal{A} = (Q, \Sigma, \delta),$$
$$q_t = \delta(q_{t-1}, \sigma_t).$$

# steps =  $T$   
definition of  $\delta$

# steps =  $O(\log T)$

# steps =  $O_{|Q|}(1)$



represented by RNNs

( shortcuts )

represented by Transformers

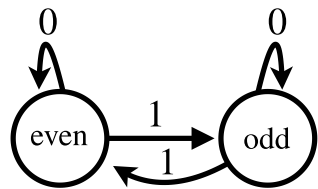
# $O(\log T)$ steps

$$\mathcal{A} = (Q, \Sigma, \delta), \\ q_t = \delta(q_{t-1}, \sigma_t).$$

Goal: compute  $q_t = \left( \delta(\cdot, \sigma_t) \circ \dots \circ \delta(\cdot, \sigma_1) \right) (q_0), t \in [T].$   
 $\delta(\cdot, \sigma): Q \rightarrow Q$

function  $\longleftrightarrow$  matrix

composition  $\longleftrightarrow$  multiplication



$Q = \{\text{even}, \text{odd}\}$   
 $\Sigma = \{0, 1\}$

parity counter

$$\delta(\cdot, 0) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix},$$

$$\delta(\cdot, 1) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$q_t = \left( \delta(\cdot, \sigma_t) \circ \dots \circ \delta(\cdot, \sigma_1) \right) q_0$$

$$\updownarrow \\ e_{q_t} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \cdots \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} e_{q_0}$$

$O(\log T)$  steps 🤔

$$\mathcal{A} = (Q, \Sigma, \delta),$$

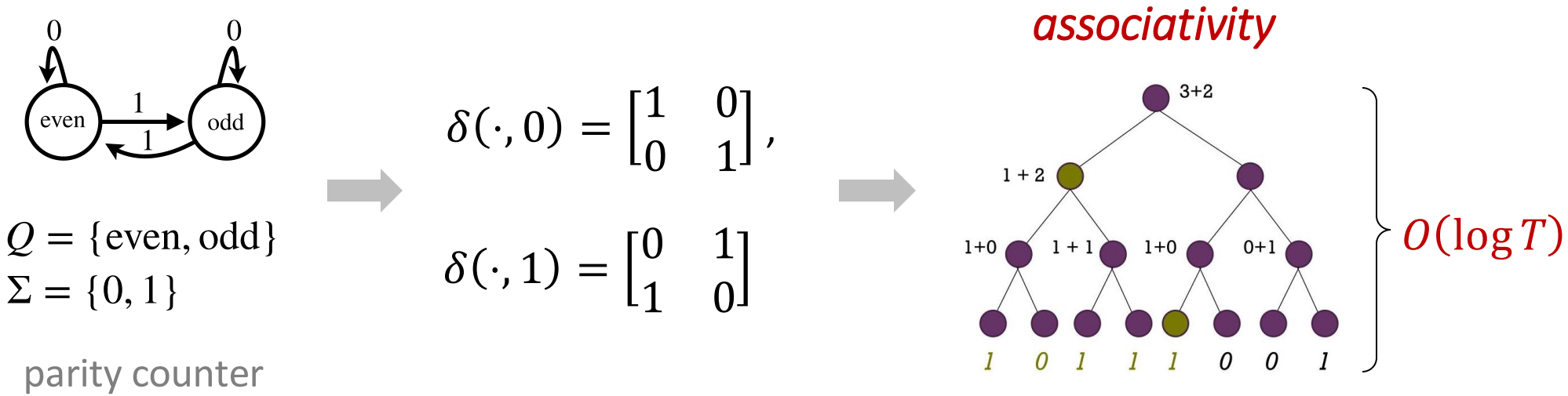
$$q_t = \delta(q_{t-1}, \sigma_t).$$

Goal: compute  $q_t = \left( \delta(\cdot, \sigma_t) \circ \dots \circ \delta(\cdot, \sigma_1) \right) (q_0), t \in [T].$

$\delta(\cdot, \sigma): Q \rightarrow Q$

function  $\longleftrightarrow$  matrix

composition  $\longleftrightarrow$  multiplication



# Can we use $o(\log T)$ layers?

We already have positive results.

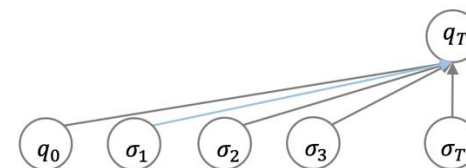
- Parity: only need to **count** #1s.

$$f \circ g = g \circ f$$

Counting works for **commutative** function composition:  **$O(1)$  layers**.

$$q_t = (\delta(\cdot, \sigma_t) \circ \dots \circ \delta(\cdot, \sigma_1))(q_0)$$

$$q_t = (\sum_{\tau \leq t} \sigma_\tau) \bmod 2$$



$$f \circ g \neq g \circ f$$

How about **non-commutative** compositions?

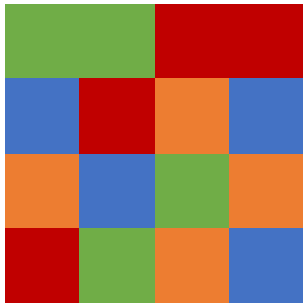
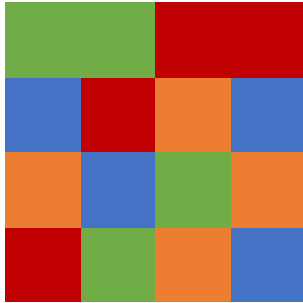
**Decomposition**



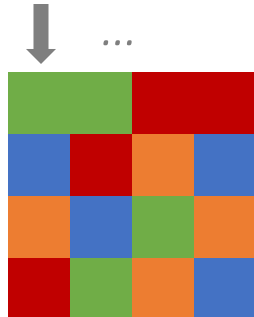
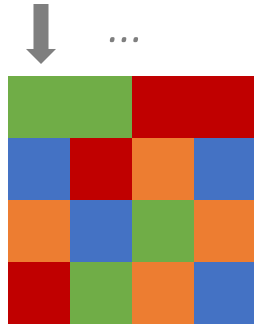
# $\tilde{O}(|Q|^2)$ steps: decomposition

Aside: “Shortcut” in recognizing visual patterns [Huang and Pashler 07]

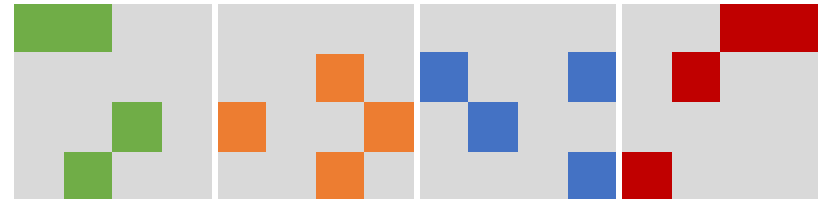
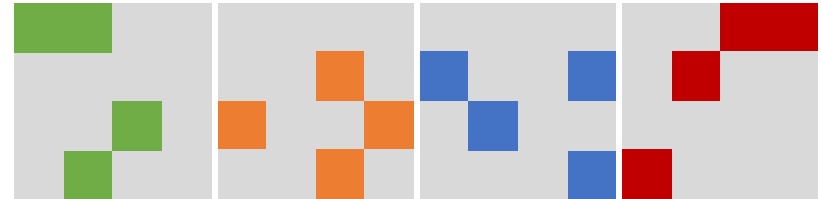
Matching?



1. tracing the cells  
one by one 🐢



2. *shortcut* via *decomposition* (color)  
(fewer sequential steps 🦅)





# Decomposition: car on a circle

$$Q = \{\text{car}, \text{car}\} \times \{0,1,2,3\}, \Sigma = \{D(\text{drive}), U(\text{U-turn})\}$$

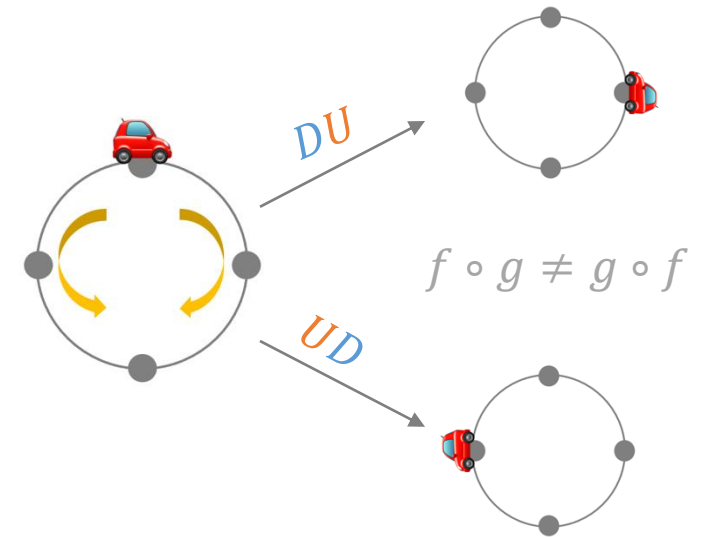
$$q_0 = (\text{car}, 0), \sigma_{1:T} = DDDUDDUUD \rightarrow q_T?$$

- Direction = **parity (sum)** of  $U$ . (parity:  $\{1, -1\} \leftrightarrow \{0, 1\}$ )
  - Position = **signed sum** mod 4 : sign = parity of  $U$ .
- }  $O(1)$  layer each

$D \ D \ D \ U \ D \ D \ U \ U \ D$

Parity: 1 1 1 -1 -1 -1 1 -1 -1 → 

Signed sum: 1 1 1 0 -1 -1 0 0 -1 → 0



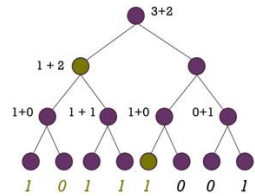
# Decomposition: general

What are we decomposing?

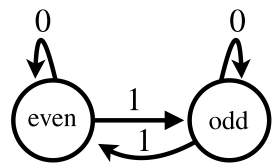


Transformation **group**:  $\mathcal{T}(\mathcal{A}) := \{\delta(\cdot, \sigma) : \sigma \in \Sigma\}$  under composition.

Recall: group axioms



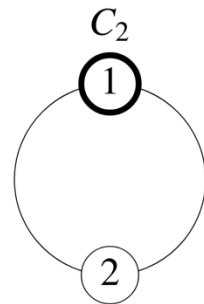
- **Associativity**:  $(a \cdot b) \cdot c = a \cdot (b \cdot c)$
- **Inverse**:  $a \cdot b = b \cdot a = e$  (**identity**)



$Q = \{\text{even}, \text{odd}\}$   
 $\Sigma = \{0, 1\}$

parity counter (mod 2)

$\mathcal{T}(\mathcal{A})$



cyclic group  $C_2$

$$\mathcal{T}(\text{Diagram with car and arrows}) = \text{Product}(C_2, C_4)$$

# Decomposition: general

Group: associative + invertible

Transformation **group**:  $\mathcal{T}(\mathcal{A}) := \{\delta(\cdot, \sigma) : \sigma \in \Sigma\}$  under composition.

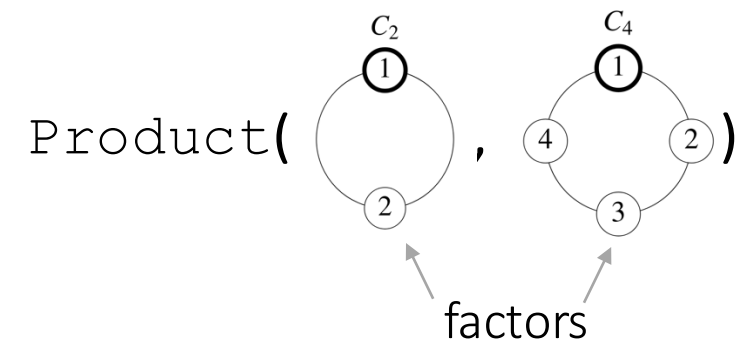
“Prime factorization” for groups:

$$G = H_n \triangleright H_{n-1} \cdots \triangleright H_1 \text{ (Jordan \& Hölder)} \quad [N = p_n \cdot p_{n-1} \cdots p_1 \text{ (Euclid)}]$$

- $H_{i-1}$  is a “factor” (normal subgroup) of  $H_i$ .  
 $\rightarrow n = O(\log |G|)$
- $H_{i+1}/H_i$  are “prime numbers” (simple groups).

If **commutative** (abelian): 1 layer

**“Solvable  $G$ ”** ... with  $O(\log |G|)$  layers ... **What is  $|G|$ ?**

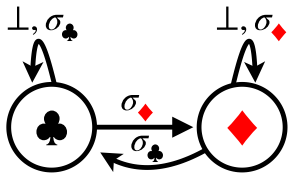


# Decomposition: general

Group: associative + **invertible**

Transformation **group**:  $\mathcal{T}(\mathcal{A}) := \{\delta(\cdot, \sigma) : \sigma \in \Sigma\}$  under composition.

Invertible:  $a \cdot b = b \cdot a = e$  (identity)



$$\delta(\cdot, \sigma_{\clubsuit}) = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$$

singular  $\rightarrow$  no inverse

$$\mathcal{Q} = \{\clubsuit, \spadesuit\}$$

$$\Sigma = \{\sigma_{\clubsuit}, \sigma_{\spadesuit}, \perp\}$$

**1-bit memory unit**

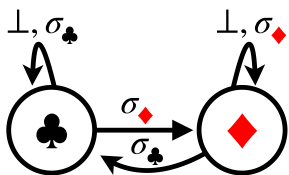
(aka. flipflop)

# Decomposition: general

Semigroup: associative (+ identity)

Transformation **semigroup**:  $\mathcal{T}(\mathcal{A}) := \{\delta(\cdot, \sigma) : \sigma \in \Sigma\}$  under composition.

Invertible:  $a \cdot b = b \cdot a = e$  (identity)



$Q = \{\clubsuit, \spadesuit\}$   
 $\Sigma = \{\sigma_{\clubsuit}, \sigma_{\spadesuit}, \perp\}$   
**1-bit memory unit**  
(aka. flipflop)

$$\delta(\cdot, \sigma_{\clubsuit}) = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$$

singular  $\rightarrow$  no inverse

$$|\mathcal{T}(\mathcal{A})| \leq O(|Q|^{|Q|})$$

i.e. with  $O(|Q| \log |Q|)$  layers  
 $\tilde{O}(|Q|)$

*Semigroup: associativity only*

Jordan & Hölder ( $\mathcal{T}(\mathcal{A})$ : group)



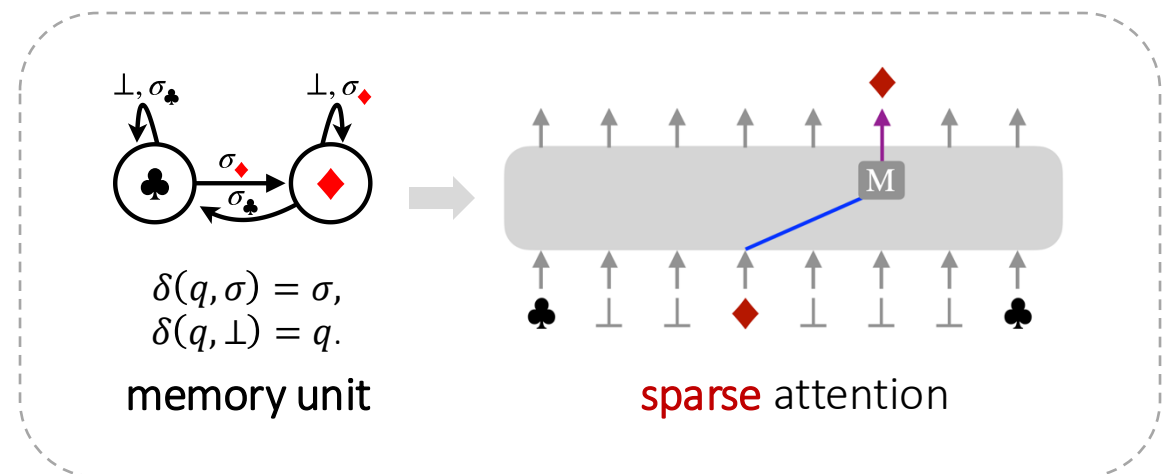
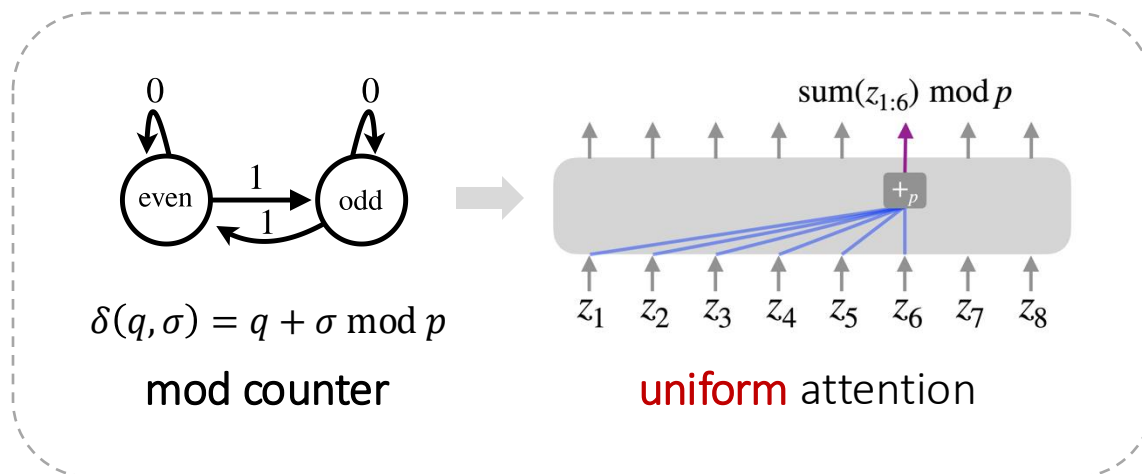
**Krohn-Rhodes** ( $\mathcal{T}(\mathcal{A})$ : semigroup)

# $\tilde{O}(|Q|^2)$ steps: decomposition

constrain the type of “factors”

#factors  $\leq \text{poly}(|Q|)$

**Krohn-Rhodes:** solvable  $\mathcal{A}$  decomposes into **2 types of factors**.



Each representable by 1 Transformer layer  
+ “gluing” with  $O(1)$  layers (using MLP).

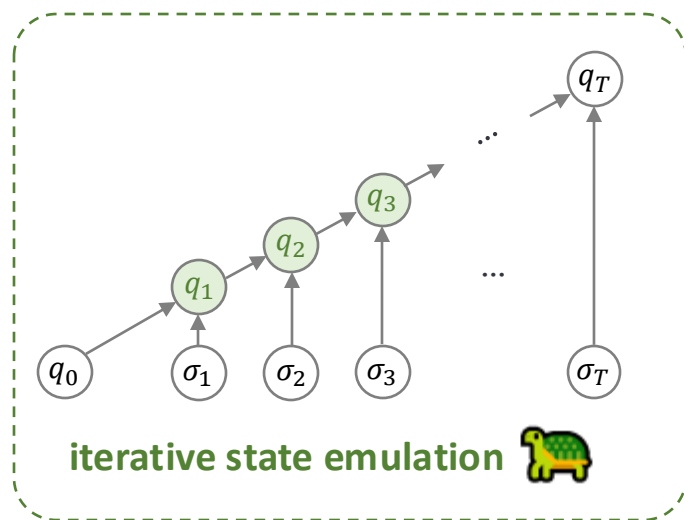
# Solutions of Reasoning

$$q_t = (\delta(\cdot, \sigma_t) \circ \dots \circ \delta(\cdot, \sigma_1))(q_0)$$

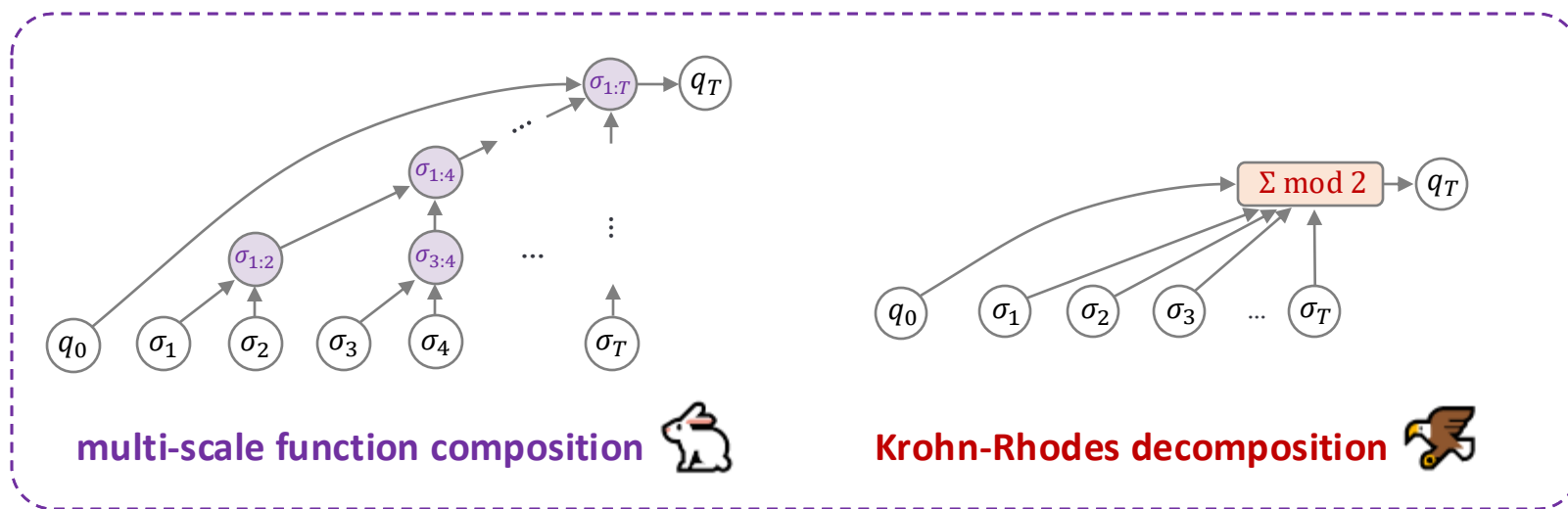
# steps =  $T$   
definition of  $\delta$

# steps =  $O(\log T)$   
associativity

# steps =  $\tilde{O}(|Q|^2)$   
algebraic structure



represented by RNNs

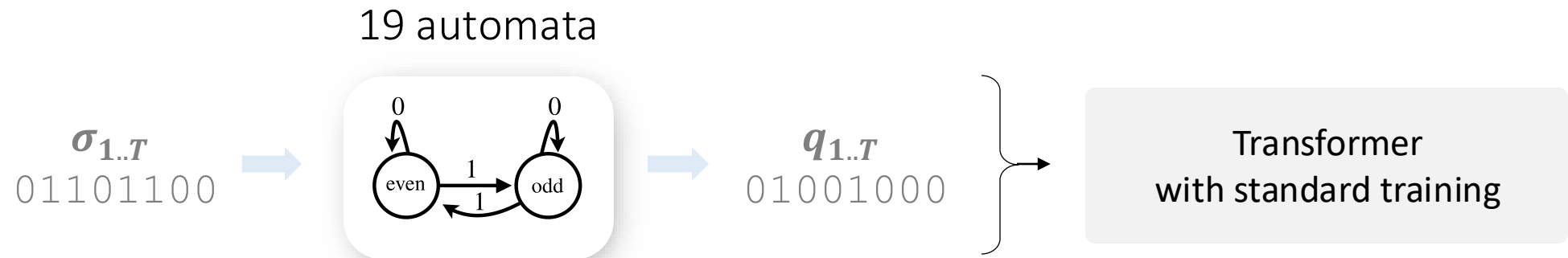


represented by Transformers

for *all*  $\mathcal{A}$

for *solvable*  $\mathcal{A}$

# Simulating $\mathcal{A}$ in practice



Can shortcuts be  
found?



# Can shortcuts be learned?

Yes, across 19 automata & 16 depths.

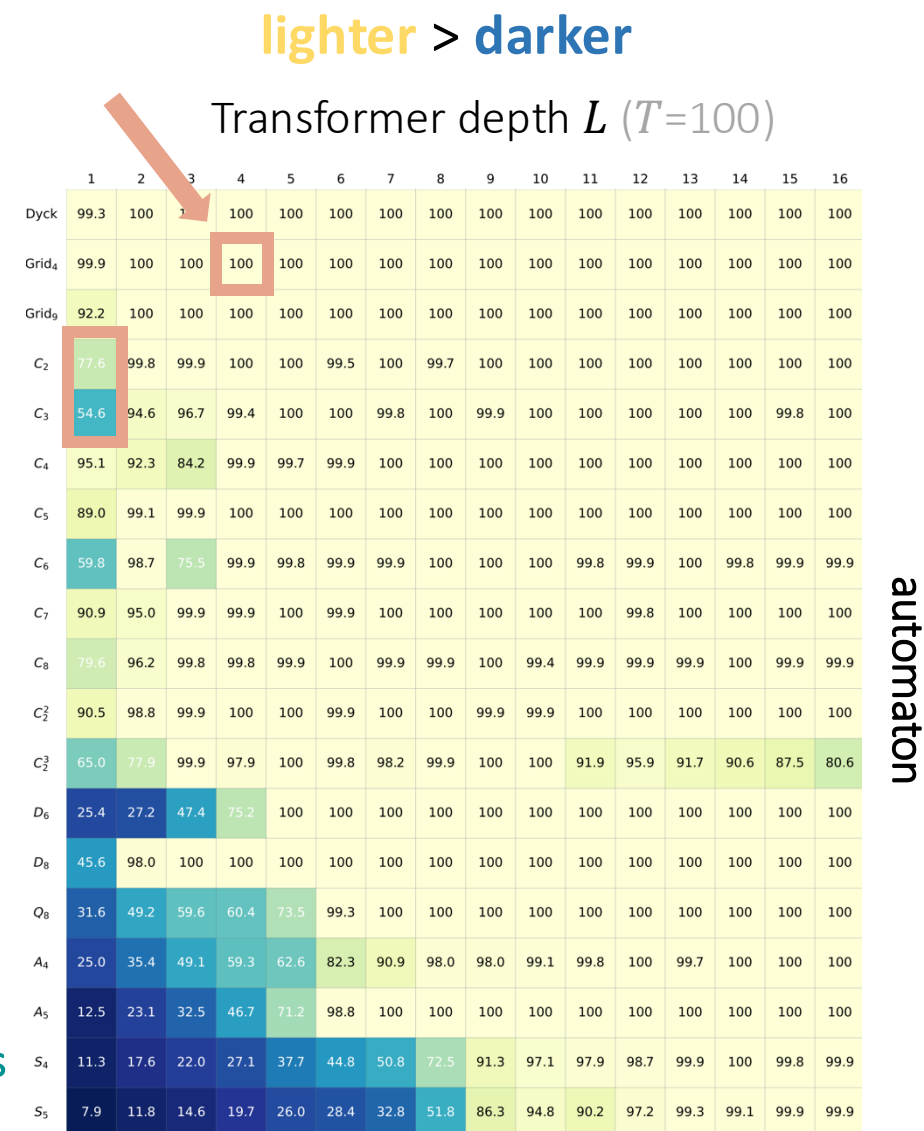
- Shortcuts are found.
- Deeper factorization  $\rightarrow$  more layers.
- Open challenges:
  - Stabilize training?
  - Interpret the solutions?

 example: Gridworld

Non-solvable groups

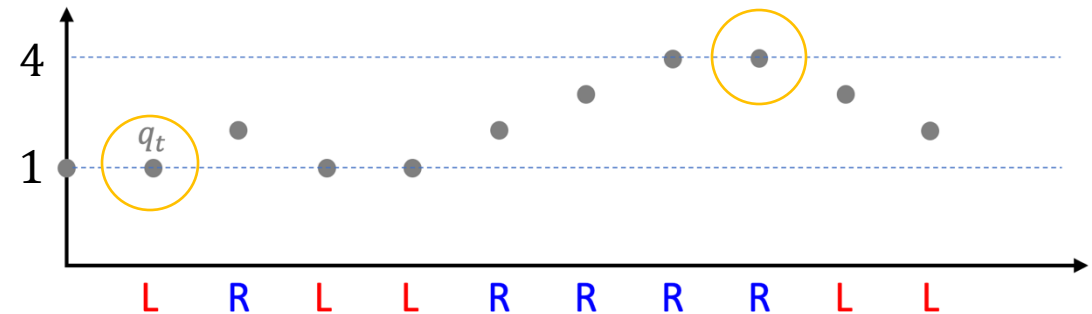
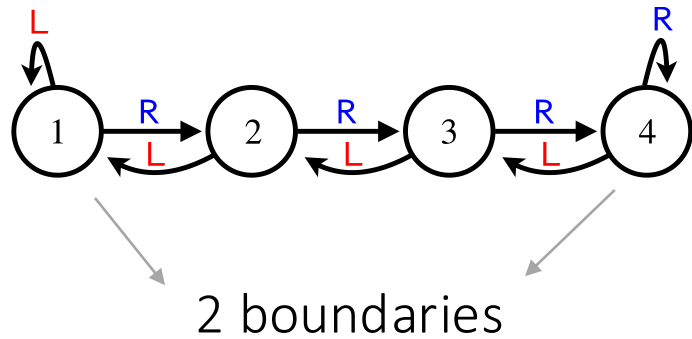
Cyclic groups  
(mod- $n$ )

Gridworld



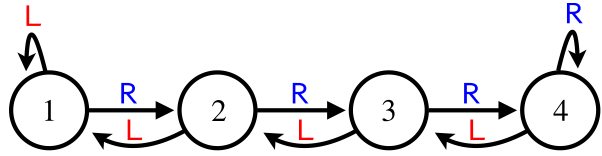
# Interpreting gridworld

1d gridworld:  $Q = \{1, 2, 3, 4\}$ ,  $\Sigma = \{\text{L}, \text{R}\}$ .



- State matters:  $\text{LR} \neq \text{RL}$  at state 1, but  $\text{LR} = \text{RL}$  at state 3.

~~"You can only figure out where you are if you know  $q_{t-1}$ ."~~

$O(1)$  layer for 

**Puzzle:** design a parallel algorithm to compute  $\sigma_{1:T} \mapsto q_{1:T}$ .

- Hint: *boundary detection*: no boundary = prefix sum.

Transformers find boundaries: 

**$O(1)$ -layer** (Krohn-Rhodes:  $\tilde{O}(|Q|^2)$ )

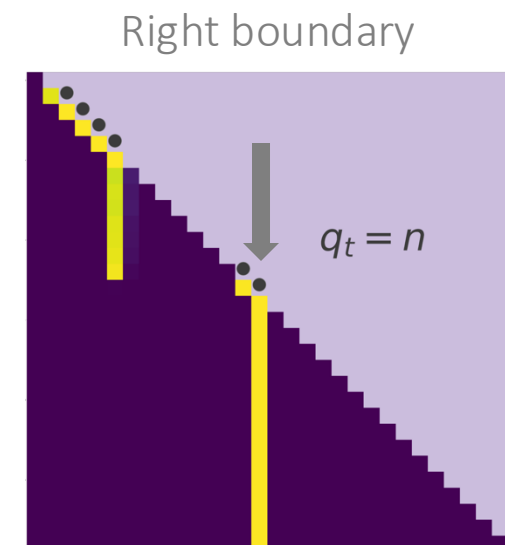
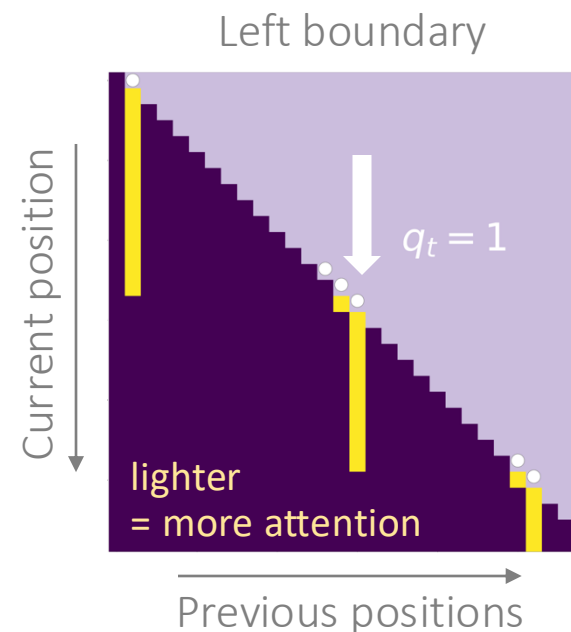
attention heatmaps

(GPT solved this before us 🤖)

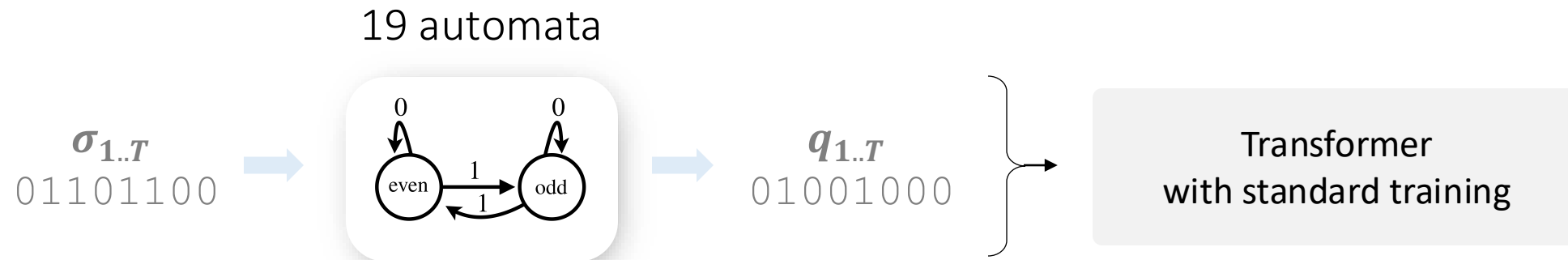
→ algorithm extracted

*“mechanistic interpretability”*

\*Caution: challenges of interpreting attention maps [WLLR NeurIPS23]



# Simulating $\mathcal{A}$ in practice



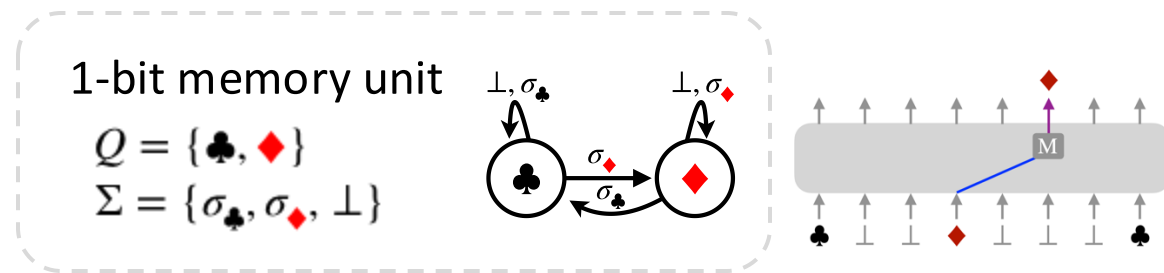
Can shortcuts  
be found?

*Yes; e.g. gridworld.*

Robust Out-Of-Distribution?

# Problems with shortcuts?

**Flip-flop:** A simple task where Transformers struggle out-of-distribution (OOD).

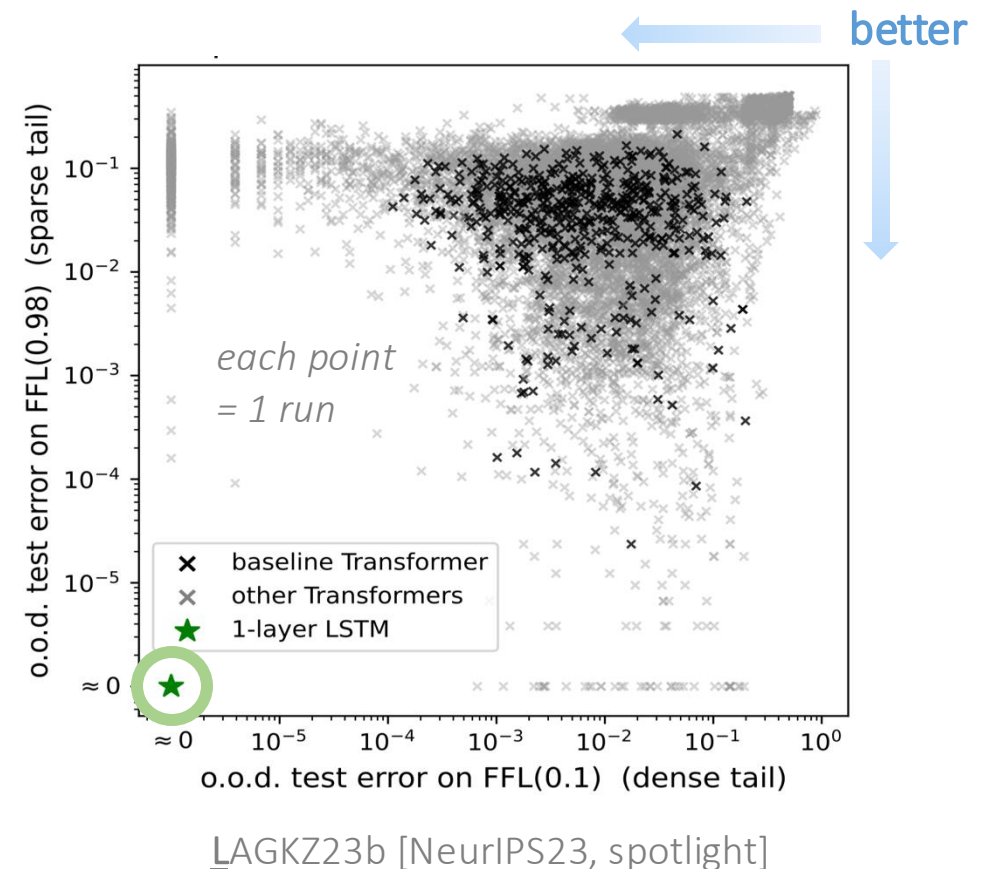


**Attention glitches:** imperfect retrieval.

- Inherent limitations of attention.
- Potential contributor to hallucination.

Mitigation: No perfect mitigations.

- unless introducing *long-tailed data* also in prior work, e.g. priming [Jelassi et al. 23].



# Flip-Flop Language Modeling (FFLM)

Flip-Flop Language (FFL): sequences of instruction-value pairs.

- 3 instructions: **w** (write) , **i** (ignore) , **r** (read).
- 2 values: {0, 1}; the value for **r** must be the same as the last **w**.

w 1 i 0 i 1 r 1 w 0 i 1 r 1

**Task:** predict values following **r** (i.e. locate the most recent **w**)



Distributions: **FFL**( $p_i$ ):  $p_w = p_r = \frac{1-p_i}{2}$ .

*Why FFLM?*

- An atomic unit underlying reasoning tasks [LAGKZ23a].
- Simple yet interesting.

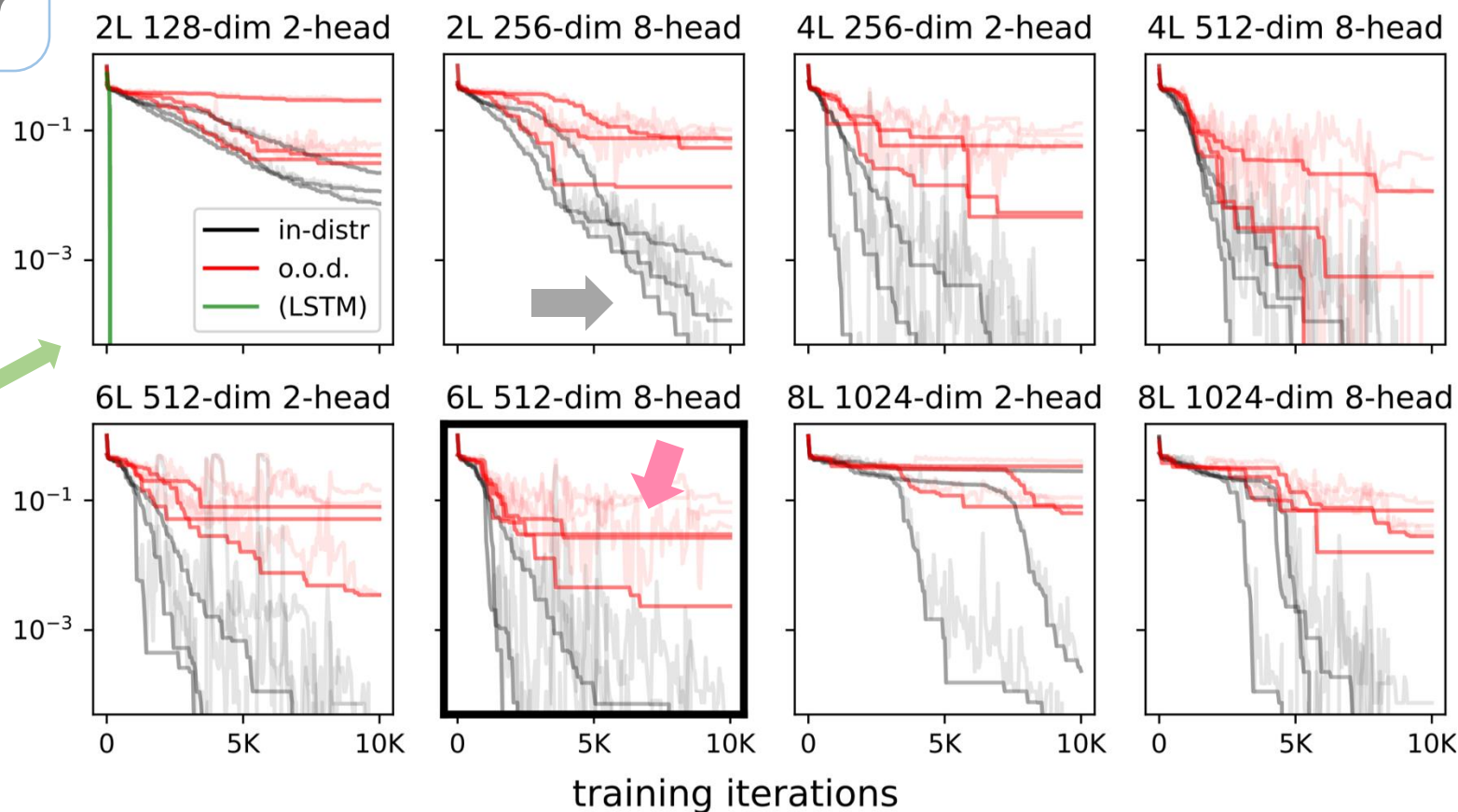
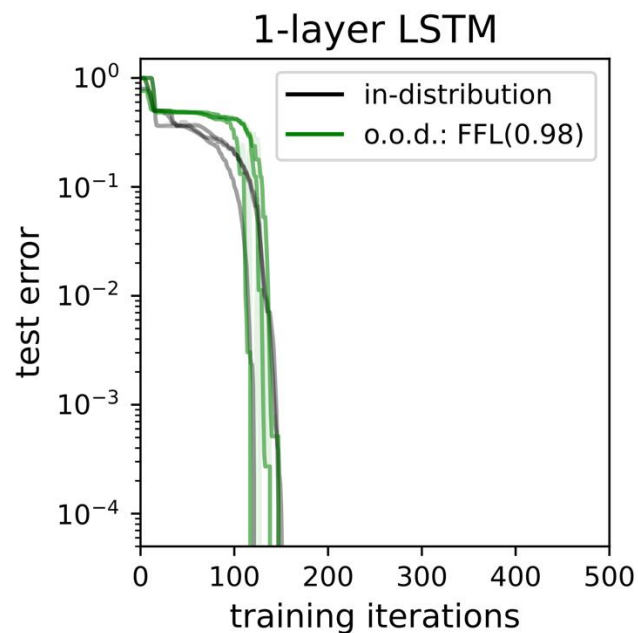
# FFLM Results

Train: FFL(0.8)  $T = 512$

Test: FFL(0.9) ... *sparser*

## Attention glitches

Transformers (20× more data & steps)



# Attention Glitches

Def: *imperfect hard retrieval*.

(R1) Transformers exhibit a long tail of errors.

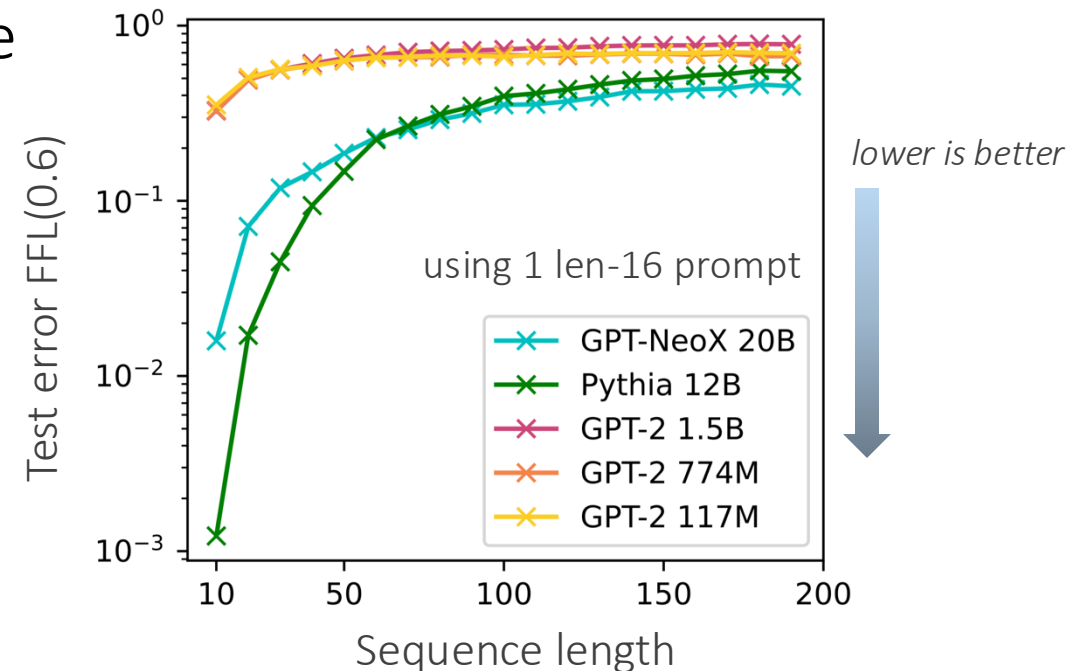
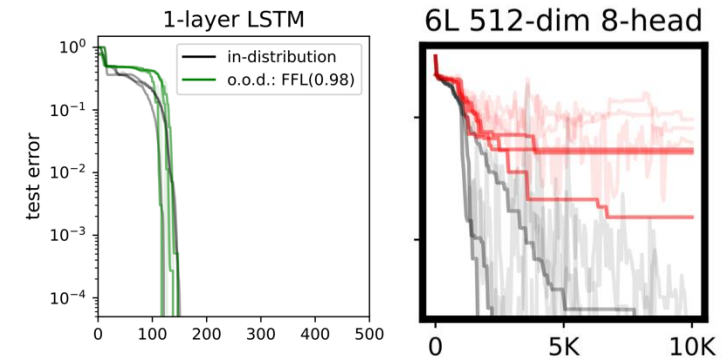
(R2) 1-layer LSTMs extrapolate *perfectly*.

(R3) 10B-scale *natural-language* models are not robust either.

w 0 i 0 i 1 w 1 i 1 i 0 r ?

Alice turns the light off.  
Then, Bob eats an apple.  
Then, Bob eats a banana.  
Then, Alice turns the light on.  
Then, Bob eats a banana.  
Then, Bob eats an apple.  
Now, the light is

FFL( $p_i$ ): various  $T$ ,  $p_w = p_r = 0.2$ .





# What causes glitching attentions?

$$\text{FFL}(p_i): p_w = p_r = \frac{1-p_i}{2}.$$

Not because of limitation on representation power (solvable with *2-layer 1-head*).

**Diluted soft attention:** caused by more items in the softmax.

$$a_{\max} = \frac{\exp(z_{\max})}{\underbrace{\exp(z_1) + \dots + \exp(z_t)}_{\text{e.g. ignores, earlier writes}} + \exp(z_{\max})}$$

- Pointed out in prior work [Hahn 20, Chiang & Cholak 22].
- Possible mitigation: scaling the logits (e.g. by  $\log T$ ), hard attention.

# What causes glitching attentions?

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**Diluted soft attention:** more items in the softmax: scaling, hard attention.

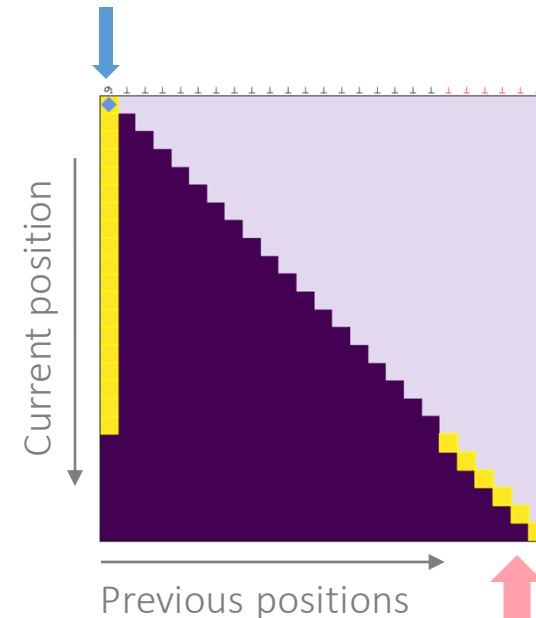
→ *failure on denser sequences (more  $w$ )*

**Wrong argmax:** hard attention won't work.

*Setting:* simple flip-flop: 1-layer 1-head.

Unlikely to precisely meet a necessary condition for linear positional encoding.

→ *failure on sparser sequences (fewer  $w$ )*



# Mitigations to attention glitches

- Incorporating OOD data.

*direct*

Ideal solution – No OOD issue if everything is in distribution! :)

- Resource scaling: larger, train for longer.  
Fresh samples → better coverage

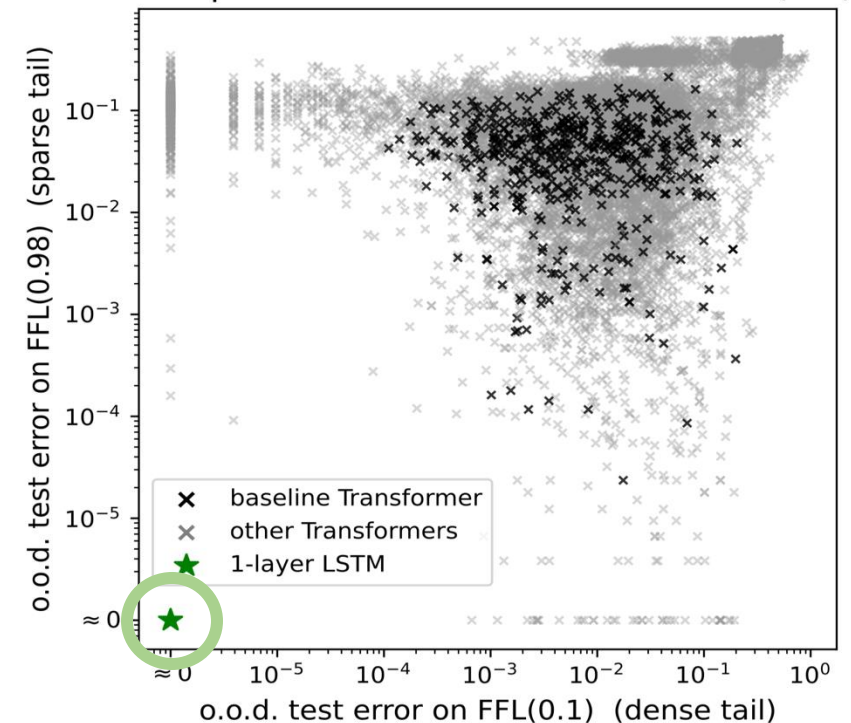
- Standard regularization  
e.g. weight decay, dropout, position encoding.

*indirect*

- Attention-sharpening losses (entropy,  $-\ell_2$ ,  $-\ell_\infty$ )

*No perfect mitigations,  
except for OOD data.*

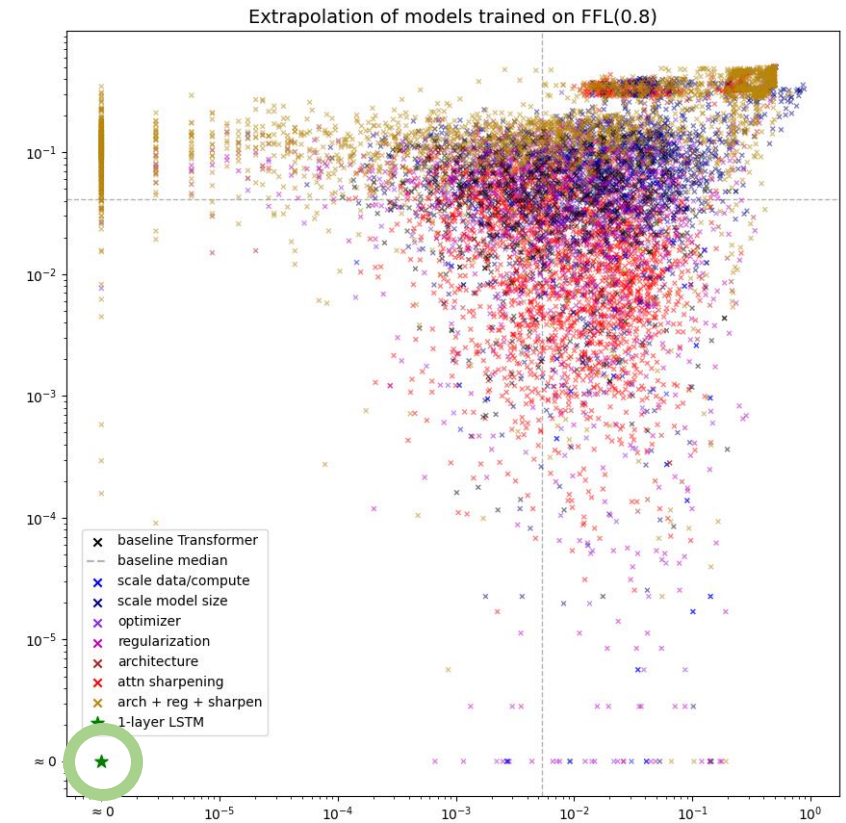
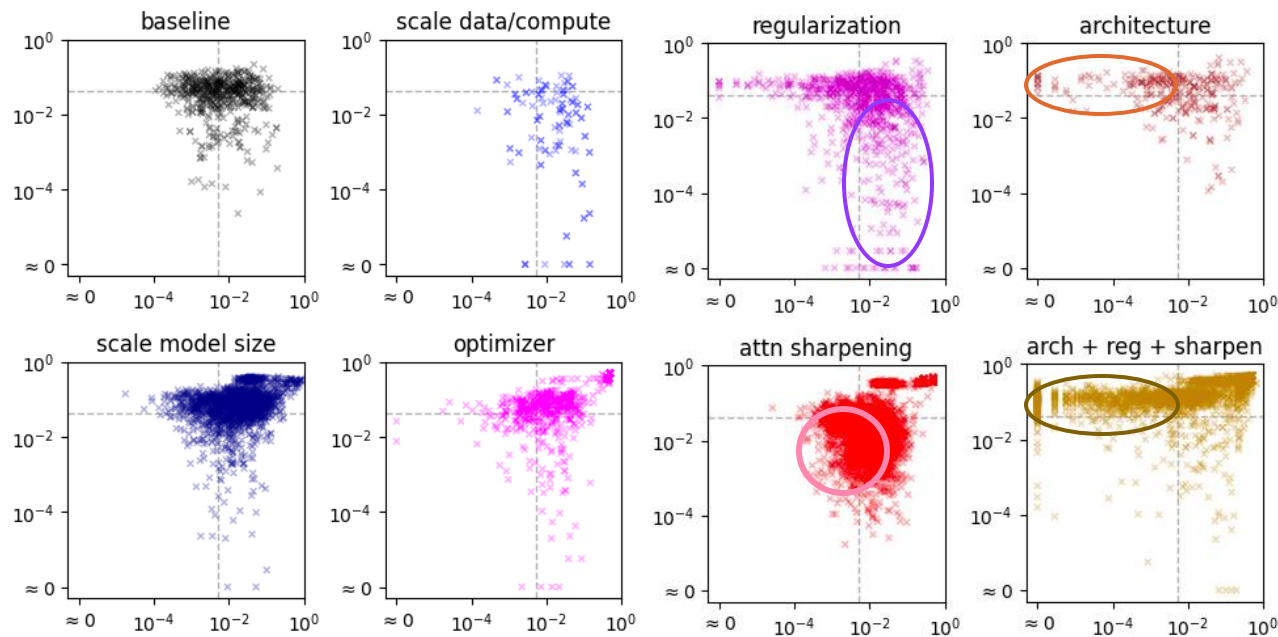
Extrapolation of models trained on FFL(0.8)



# Attention glitches: no perfect mitigations

Dense-sparse trade-off: seldom improve both.

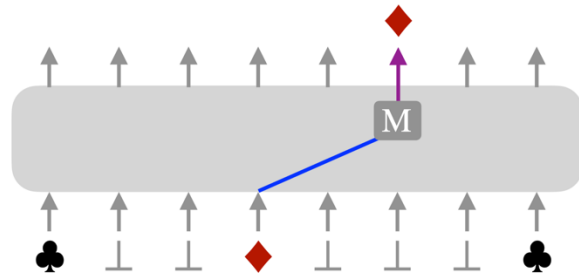
*denser = x-axis, sparser = y-axis.*



LSTM

# OOD failures – the 2 atomic units

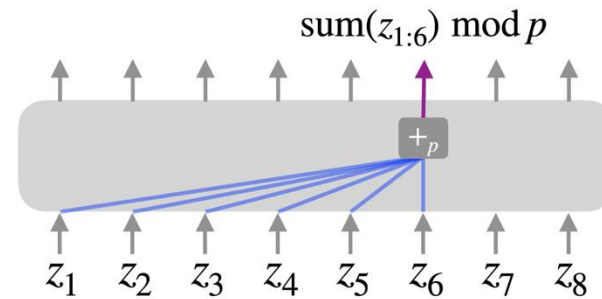
- Flip-flop → **sparse** attention



**Attention:** Flip-Flop Language Modeling

*... the simplest setup where  
(closed-domain) hallucination occurs.*

- Parity → **uniform** attention

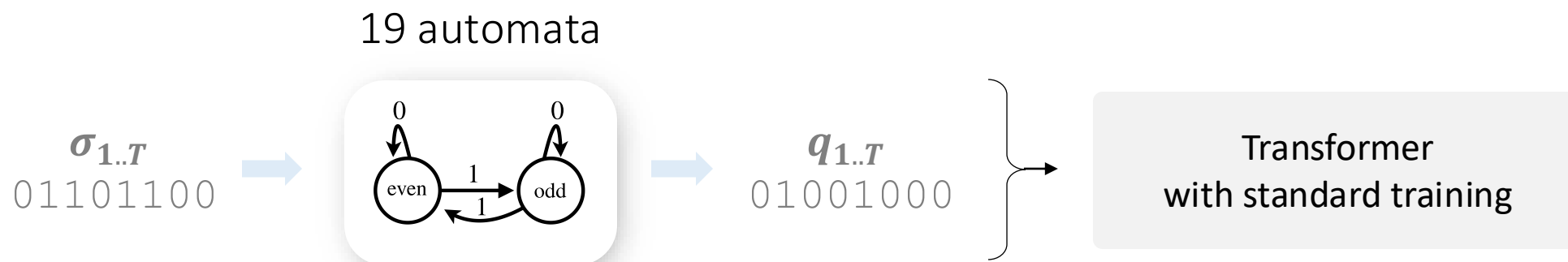


$$\text{MLP: } q_t = \left( \sum_{i \in [t]} \sigma_i \right) \bmod 2$$

↓  
memorized → fail at unseen  $\left( \sum_{i \in [t]} \sigma_i \right)$ .  
(failure of ReLU [Xu 20])

**Solution:** **periodic activation**, e.g.  $\sin(x)$ .

# Empirical results



Can shortcuts  
be found?

*Yes; e.g. gridworld.*

Robust Out-Of-Distribution?

*Failure of: 1. Attention (flipflop)  
2. MLP (parity)*

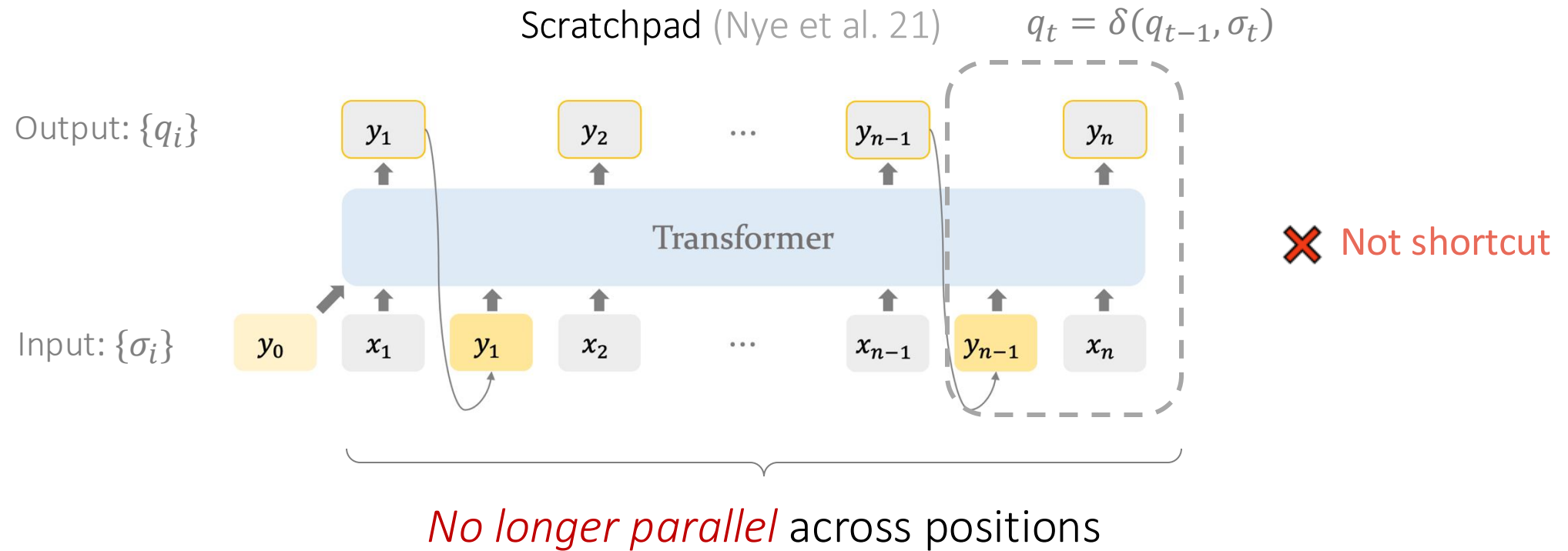
Any fixes?

**Computational shortcuts** exist, but practical **statistical shortcuts** are brittle.

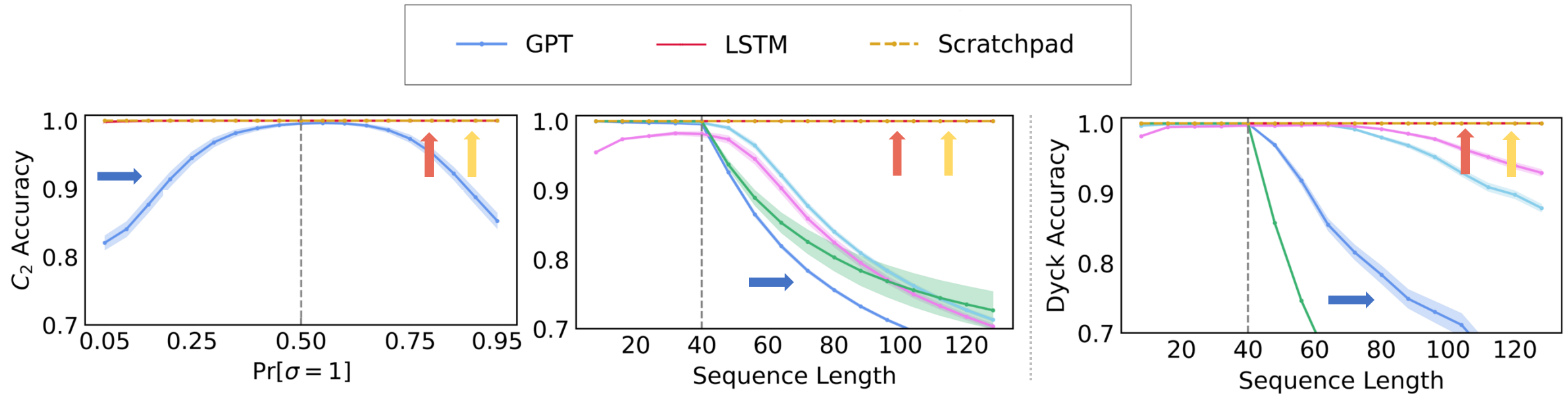


# Autoregressive mode of Transformers

Fix to OOD: *iterative/autoregressive* solutions: use  $q_{t-1}$  as inputs.



# Autoregressive mode of Transformers




Transformers generalize, when made autoregressive with **scratchpad** [Nye et al. 22].

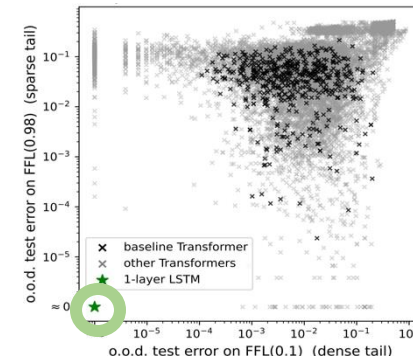
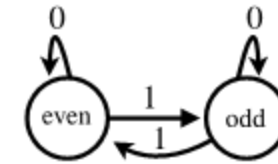
→ Can we learn *shortcuts that generalize?* ... attention glitches (flipflop)



# Transformers Learn Shortcuts to Automata

Parallel solutions to sequential reasoning problems.

- **Theory:** Transformers learns  $o(T)$  layers *shortcuts*.
  - All  $\mathcal{A}$ :  $O(\log T)$  layers: divide-and-conquer.
    - This is also the lower bound for the general case.
  - All *solvable*  $\mathcal{A}$ :  $O_{|Q|}(1)$  layers: **Krohn-Rhodes Theory**.
    - Special case:  $O(1)$ -layer simulation. 
- **Empirical study:** shortcuts can be found in practice.
  - *Benefit:* sequential computation steps  $\ll$  reasoning steps.
  - *Weakness:* the shortcuts are **brittle OOD, hallucination**.
    - **No perfect parallel solutions yet.**



# Discussions

*What can we learn from small-scale experiments?*

- FFLM extensions: more values, selection criteria (multi-step reasoning).
- What insights transfer across scale? e.g. sharpen attention for code/math?

*Perfect accuracy?* More comprehensive metrics; understand the errors.

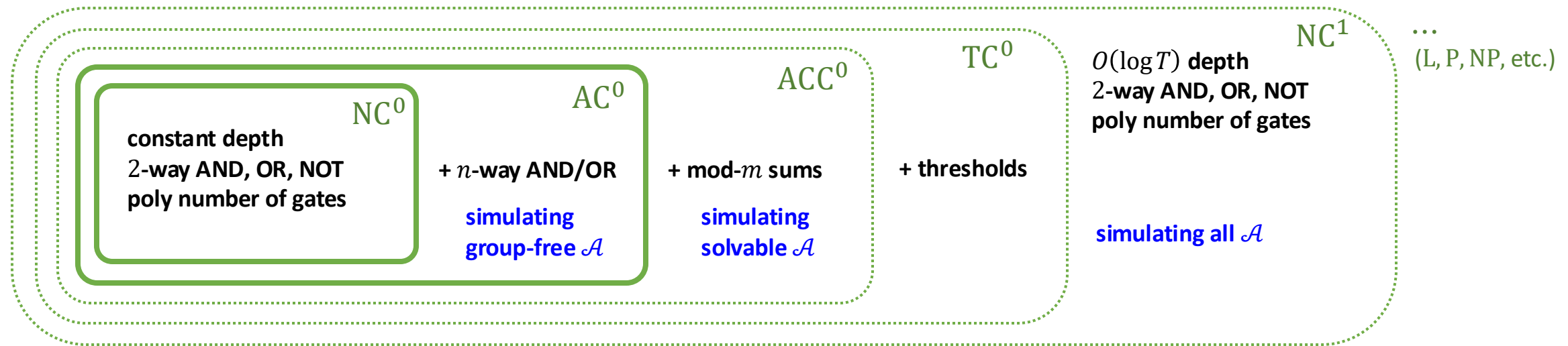
*Architectural changes?* e.g. recurrence, Mamba (S6), built-in operators.

*Theory?* Representational, optimization (stability), generalization.

# Appendix

# Quantifying efficient parallel circuits

- **Goal:** formalize “Krohn-Rhodes implies efficient simulation”
- Low-depth parallel algorithms are best captured by **circuit complexity**








Embarrassingly open: are any of the ☐ proper?  $ACC^0 \stackrel{?}{=} NP$  ? 

# Factorization: from integers to groups

$$8 = 2 \times 2 \times 2$$

- Why groups get complicated: **combinatorial explosion**

  $C_8$ : mod-8 addition  
  $E_8 \cong C_2 \times C_2 \times C_2$ : 3-bit vectors under XOR  
  $C_4 \times C_2$ : non-interacting mod-4 & parity  
  $D_8 \cong C_4 \rtimes C_2$ : rotations/reflections of a square  
  $Q_8$ : multiplication of unit quaternions

} **non-abelian:**  $gh \neq hg$

- **Finite group theory:** classical toolbox for understanding symmetries

$$C_8, E_8, C_4 \times C_2, D_8, Q_8 \leq (C_2 \wr C_2) \wr C_2$$

**Jordan-Hölder factors** (simple groups)

**Krasner-Kaloujnine embedding** (wreath product)

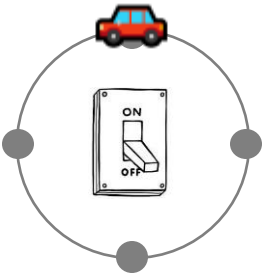
# Decomposition: the glue

$$\mathcal{T}(\text{car on a circular track}) = \text{Product}(\text{C}_2, \text{C}_4)$$

Direct product  $\times$ , e.g. 🦓  $C_4 \times C_2$

Two *independent* groups

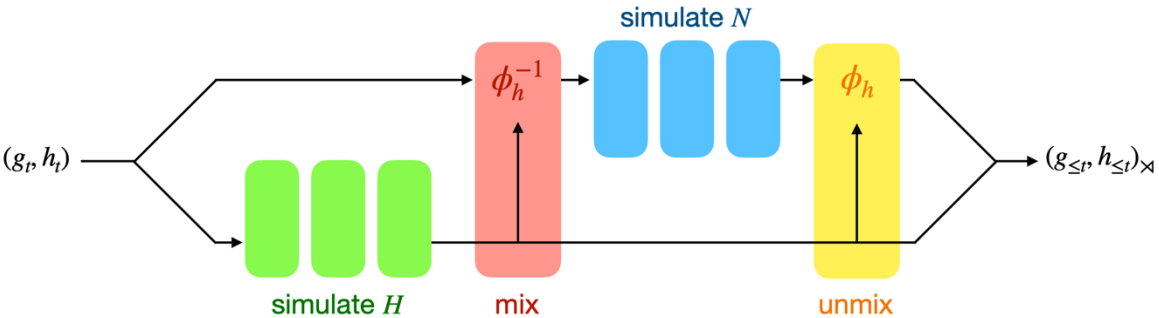
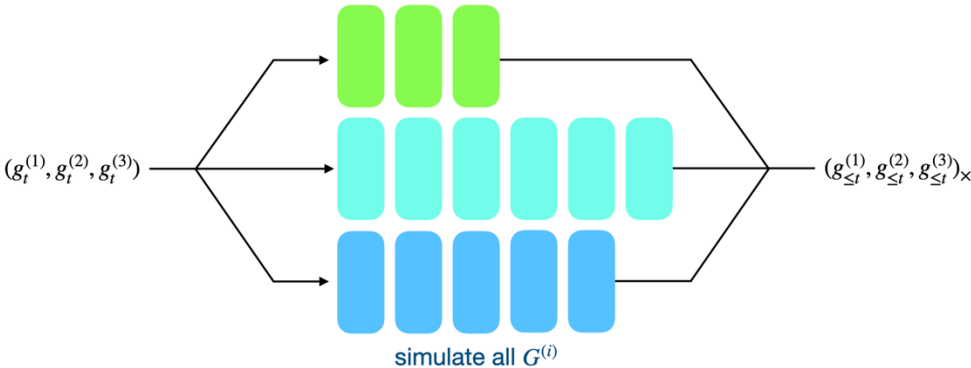
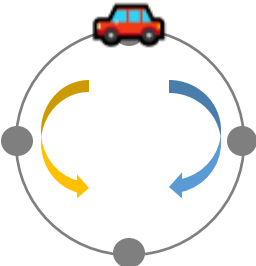
- $(g_1, h_1) \cdot (g_2, h_2) = (g_1 g_2, h_1 h_2)$
- e.g. car + a light switch



Semidirect product  $\rtimes$ , e.g. 🦀  $D_8 \cong C_4 \rtimes C_2$

Two *interacting* groups

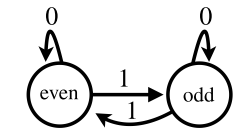
- $(g_1, h_1) \cdot (g_2, h_2) = (g_1 h_2 g_2 h_2^{-1}, h_1 h_2)$
- e.g. car + direction toggle



# Transformation semigroups

$$q_t = (\delta(\cdot, \sigma_t) \circ \dots \circ \delta(\cdot, \sigma_1))(q_0)$$

$\mathcal{T}(\mathcal{A}) := \{\delta(\cdot, \sigma) : \sigma \in \Sigma\}$  under composition (associativity).



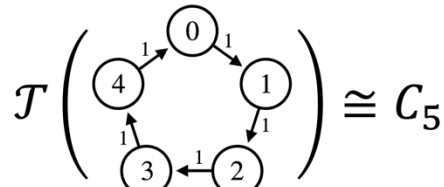
$Q = \{\text{even}, \text{odd}\}$   
 $\Sigma = \{0, 1\}$

parity counter

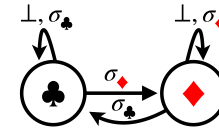
$\mathcal{T}(\mathcal{A})$

	0	1
0	0	1
1	1	0

cyclic group  $C_2$



$\mathcal{T} \left( \begin{array}{c} \text{0} \\ \text{1} \\ \text{2} \\ \text{3} \\ \text{4} \end{array} \right) \cong C_5$   
 cyclic group  $C_5$



$Q = \{\clubsuit, \diamondsuit\}$   
 $\Sigma = \{\sigma_{\clubsuit}, \sigma_{\diamondsuit}\}$

1-bit memory unit

$\mathcal{T}(\mathcal{A})$

	$\sigma_{\diamondsuit}$	$\sigma_{\clubsuit}$	$\perp$
$\sigma_{\diamondsuit}$	$\sigma_{\diamondsuit}$	$\sigma_{\diamondsuit}$	$\sigma_{\diamondsuit}$
$\sigma_{\clubsuit}$	$\sigma_{\clubsuit}$	$\sigma_{\clubsuit}$	$\sigma_{\clubsuit}$
$\perp$	$\sigma_{\diamondsuit}$	$\sigma_{\clubsuit}$	$\perp$

flip-flop monoid

} non-invertible

**Group  $G$ :** a set  $G$  with operation  $G \times G \rightarrow G$ .

- Associativity:  $(a \cdot b) \cdot c = a \cdot (b \cdot c)$
- Identity:  $a \cdot e = e \cdot a = a$
- Inverse:  $\forall a \in G, \exists b \in G$  s.t.  $a \cdot b = b \cdot a = e$

**Semigroup  $G$ :** a generalization of group.

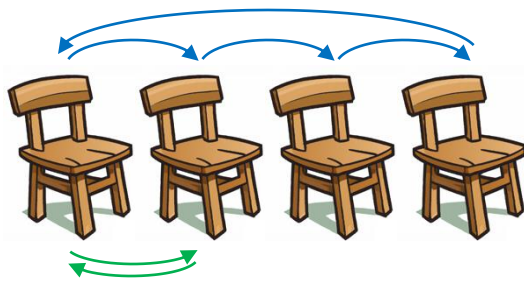
- Associativity.
- (+ Identity: a *monoid*.)

# What about *semigroups*?

$$\mathcal{T}(\mathcal{A}) := \{\delta(\cdot, \sigma) : \sigma \in \Sigma\} \text{ under composition}$$

More complicated: **rank collapses**.

***n*-player musical chairs**



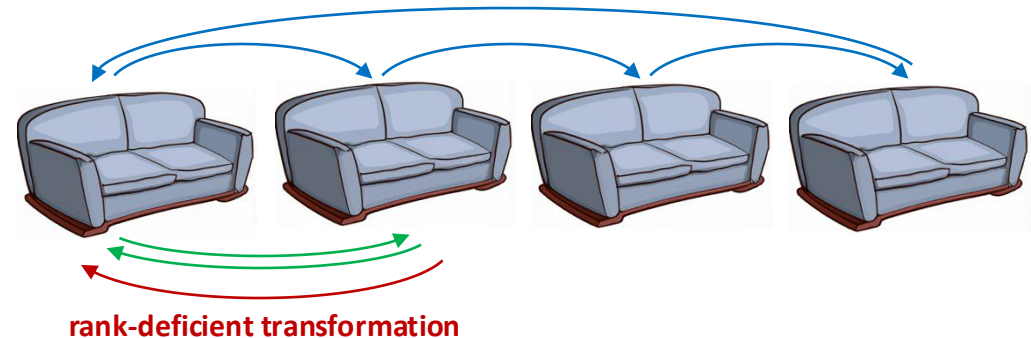
$Q = \{\text{positions of } n \text{ players}\}$

$\Sigma = \{ \text{cycle, swap} \}$

$$\begin{bmatrix} 1 & & & 1 \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix} \quad \begin{bmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix}$$

$\mathcal{T}(\mathcal{A}) = S_n$ : all ***n*!** permutations on  $[n]$

***n*-player musical **sofas****



$Q = \{\text{positions of } n \text{ players}\}$

$\Sigma = \{ \text{cycle, swap, merge} \}$

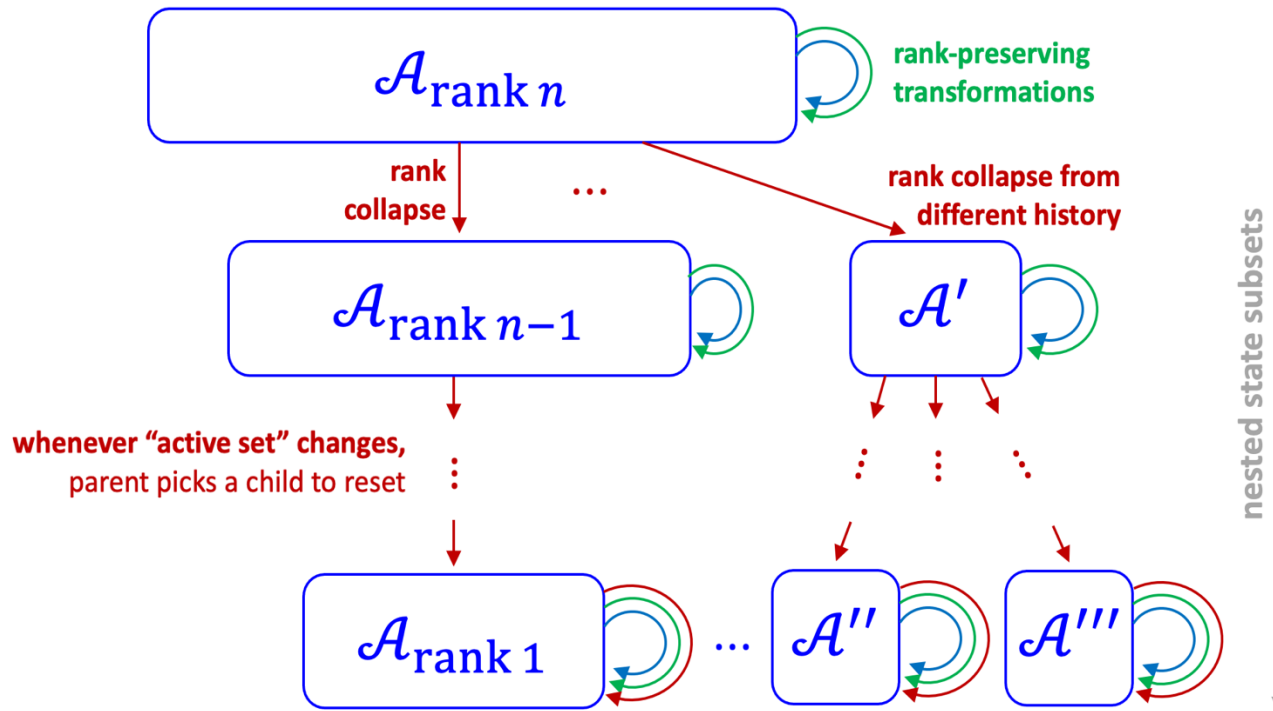
$$\begin{bmatrix} 1 & & & 1 \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix} \quad \begin{bmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix} \quad \begin{bmatrix} 1 & 1 & & \\ & & & \\ & & & 1 \\ & & & & 1 \end{bmatrix}$$

$\mathcal{T}(\mathcal{A}) = T_n$ : all ***n<sup>n</sup>*** functions  $[n] \rightarrow [n]$



# Krohn-Rhodes Intuitions

Tracking rank collapses (*holonomy decomposition*)



Number of layers: (recall:  $|G| \leq n^n$ )

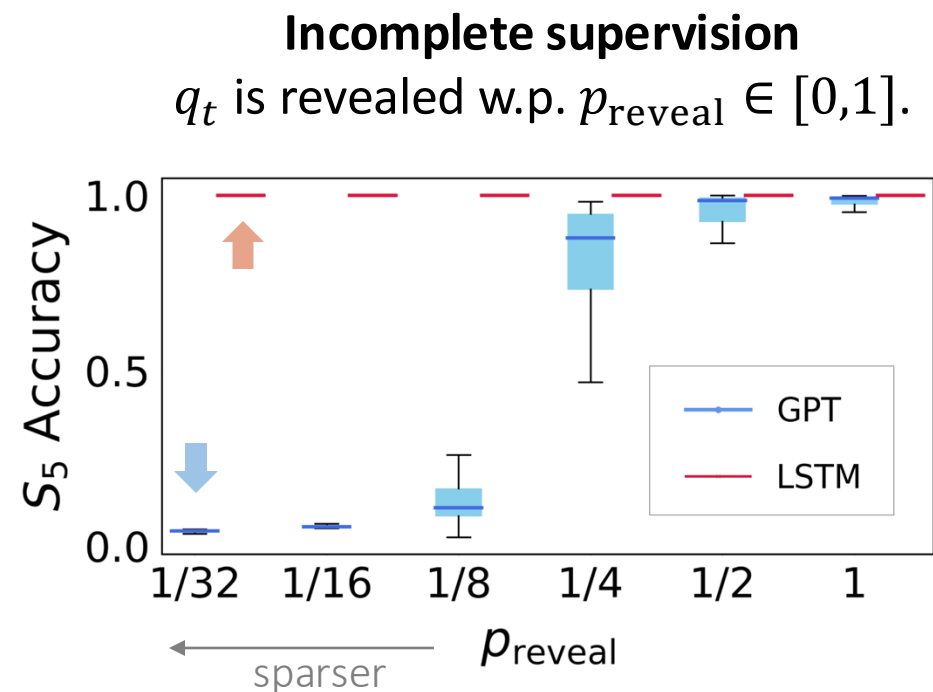
- Solvable groups:  $O(\log |G|)$ 
  - mod counter
- Permutation-reset semiautomaton:  $O(\log |G|) + 2 \leq O(|Q| \log |Q|)$ .
  - mod counter + memory unit
- Semiautomaton:  $\leq |Q|$  levels.

# Training with limited supervision

*Less ideal setups?*

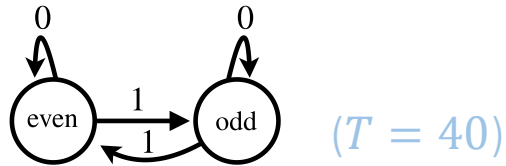
**Indirect supervision**  
train & test on a function of  $q_t$ .

Dyck <sub>4,8</sub>	Grid <sub>9</sub>	$S_5$	$C_4$	$D_8$
stack top	$\mathbb{1}_{\text{boundary}}$	$\pi_{1:t}(1)$	$\mathbb{1}_{0 \bmod 4}$	location
100.0	99.8	99.8	99.7	99.8



LSTM is always 100% → Open: *How to improve Transformer training?*

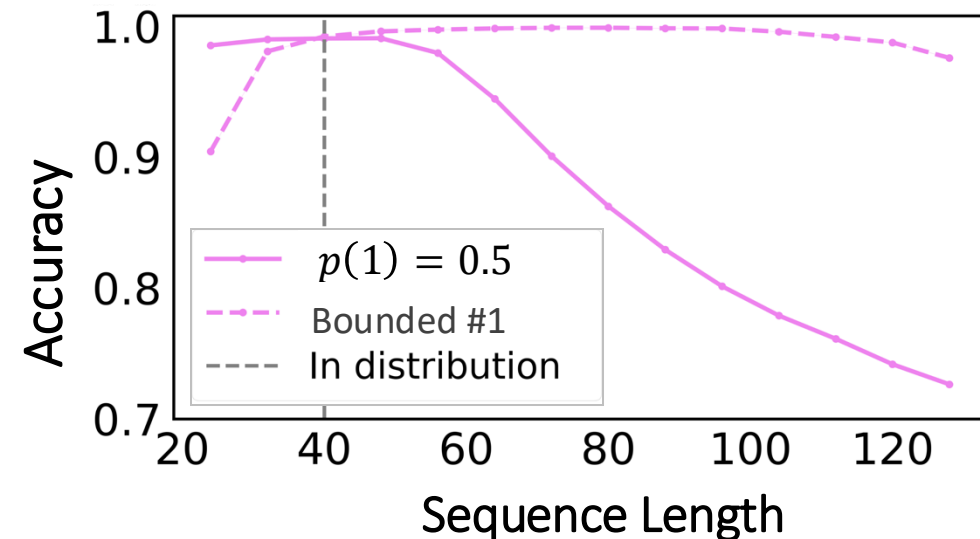
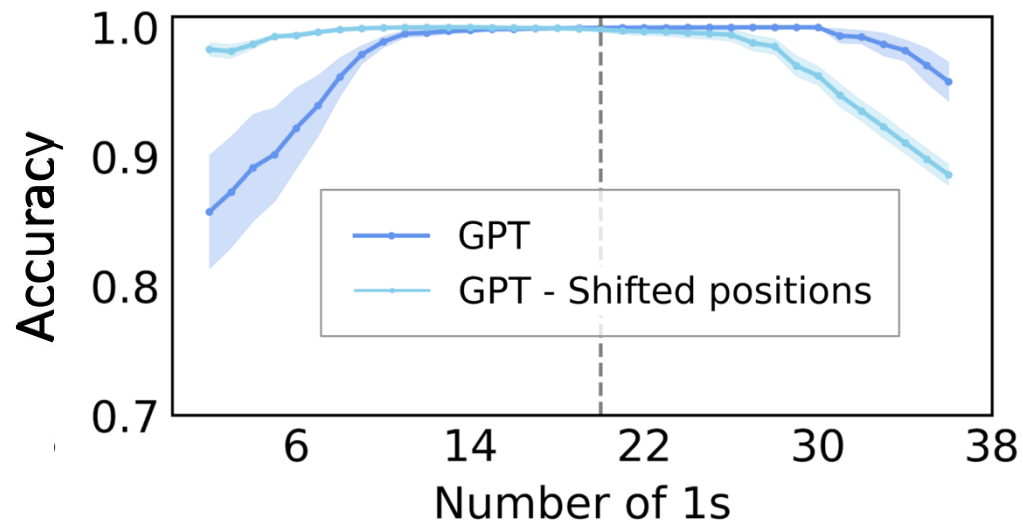
# OOD Generalization - Parity



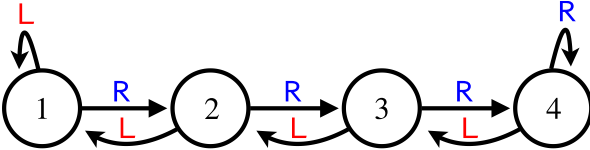
- train:  $p(1) = 0.5$
- test: other  $p(1)$ .

$$q_t = \underbrace{\left(\sum_{i \in [t]} \sigma_i\right)}_{\text{concentrates } \approx p(1) \cdot t} \underbrace{\text{mod } 2}_{\text{memorized by MLP}}$$

→ fail at unseen  $\left(\sum_{i \in [t]} \sigma_i\right)$ .

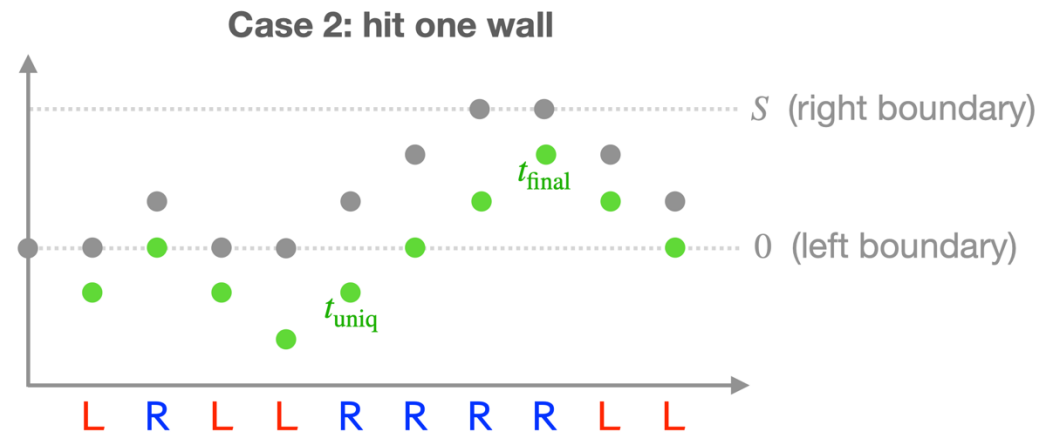
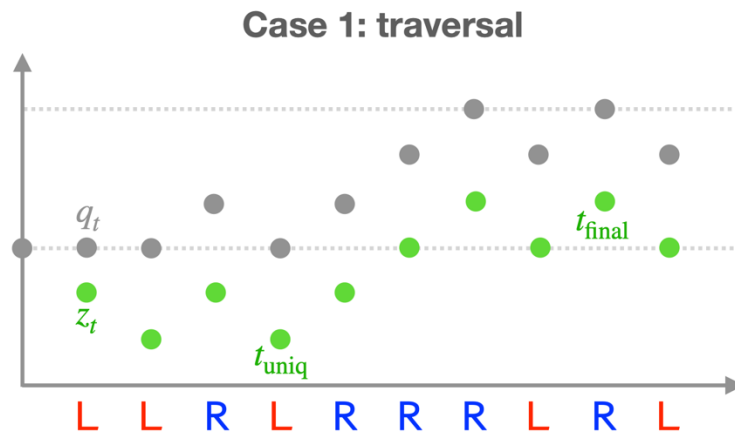


$O(1)$  layer for



- Parallel boundary detector:

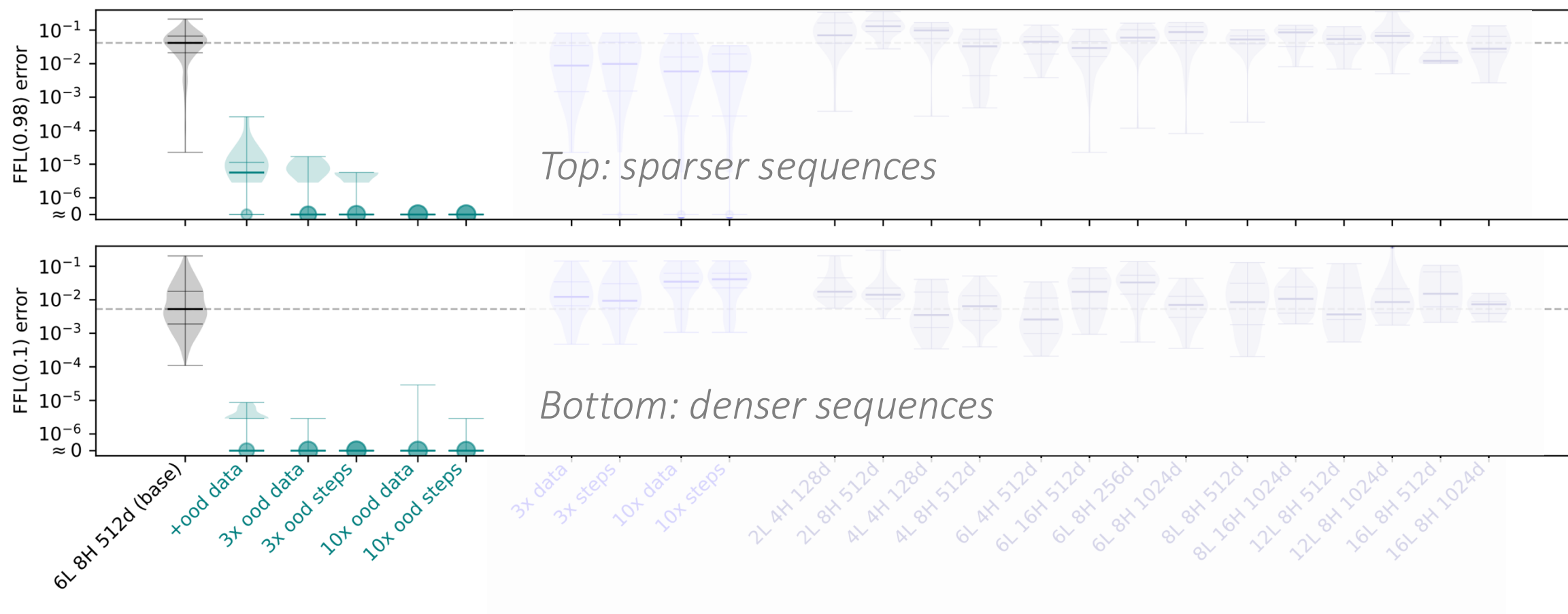
- Compute prefix sums  $z_t := \sum \sigma_{1:t}$  (ignoring boundaries);
- At each  $t$ , find most recent  $t_{\text{uniq}} < t$  such that  $z_{t_{\text{uniq}}:t}$  has  $n(\text{\#states})$  unique values;
- Then  $t_{\text{final}} := \max_{t_{\text{uniq}} \leq \tau \leq t} (\text{argmax } z_\tau, \text{argmin } z_\tau)$  is last boundary collision.



# Direct mitigations

(R4) Incorporating OOD data (“*priming*”) works the best, by far.

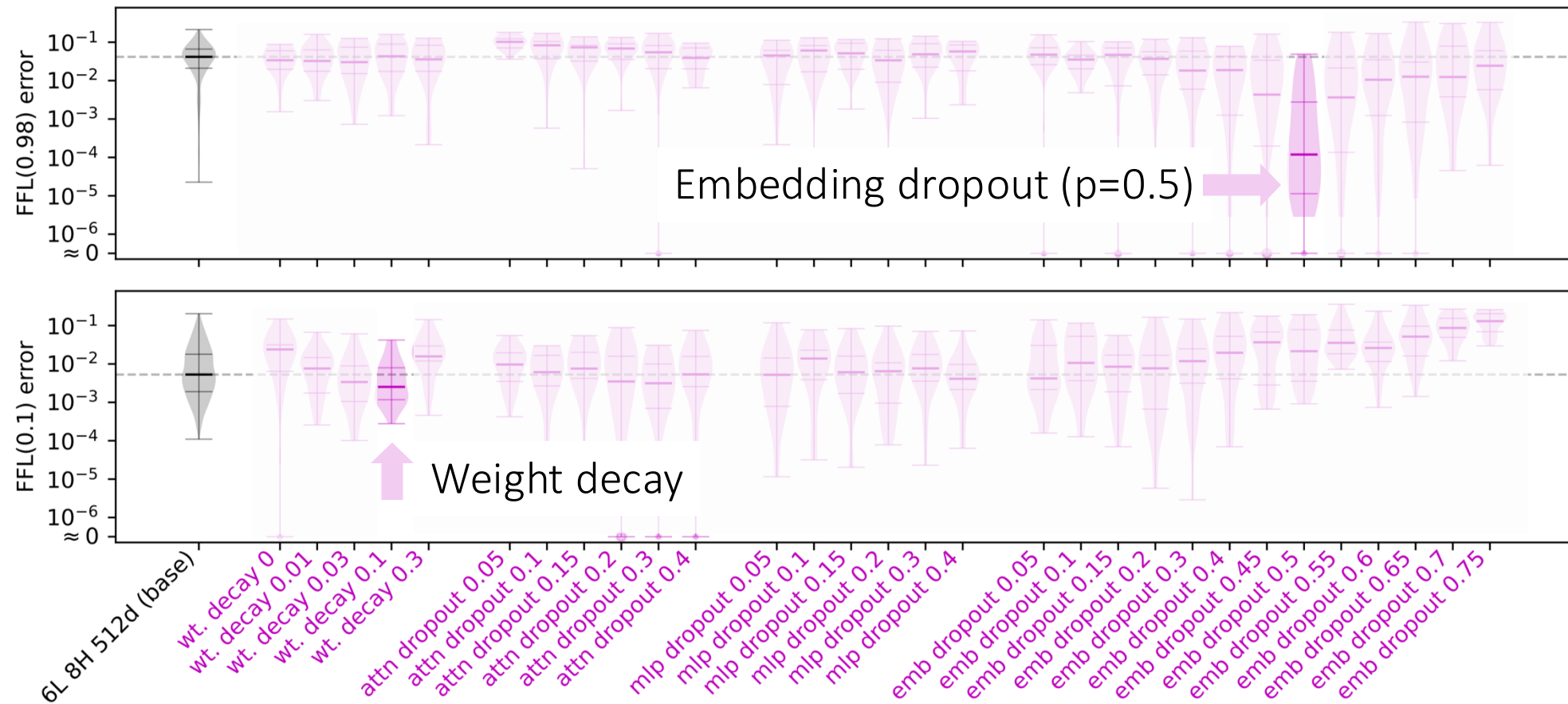
[Jelassi 23]



# Indirect mitigations

- Weight decay
- Dropout (attention, MLP, embedding)

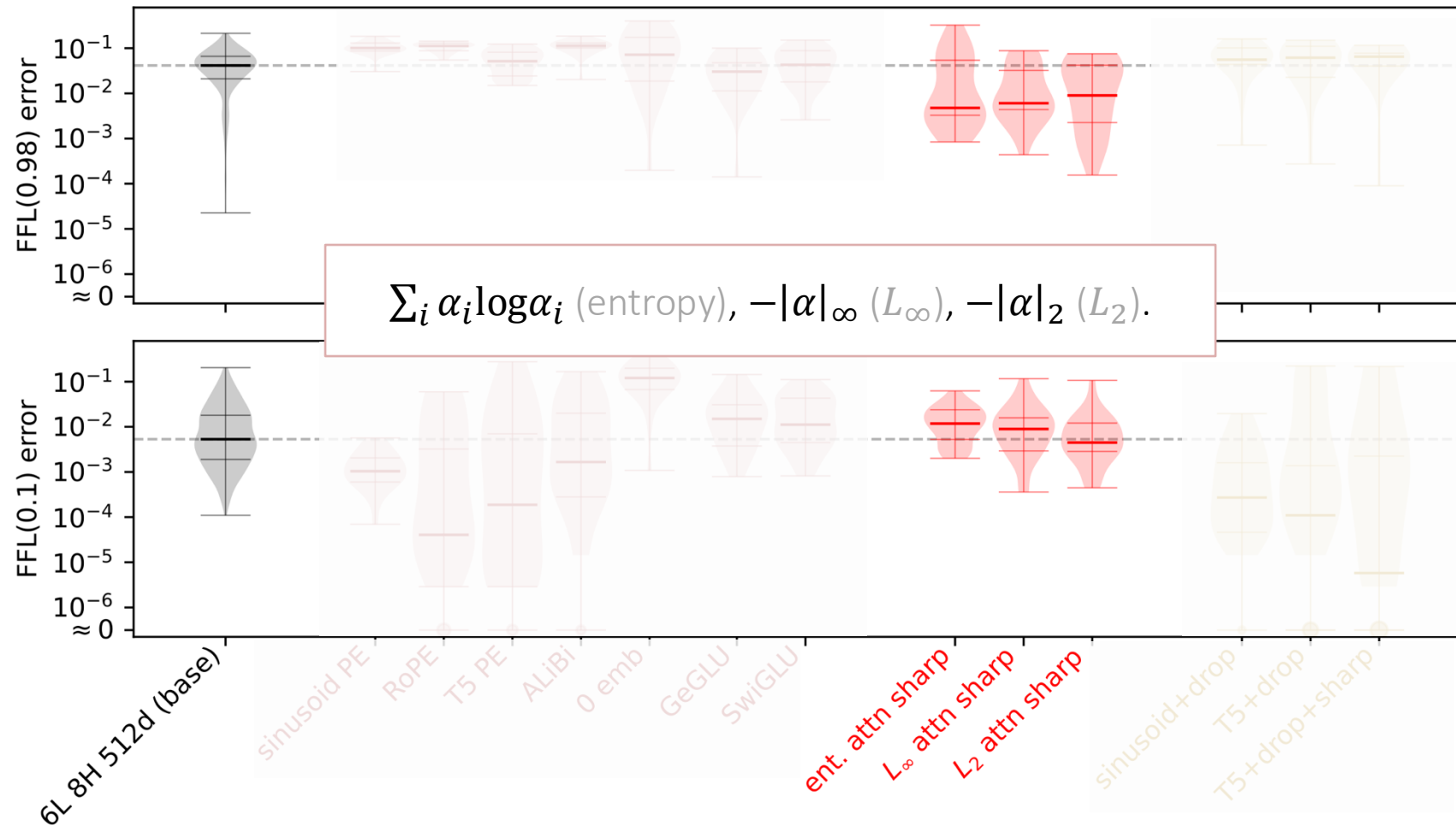
(R6) Standard regularizations have various influences.



# Indirect mitigations

Attention-sharpening  
regularization

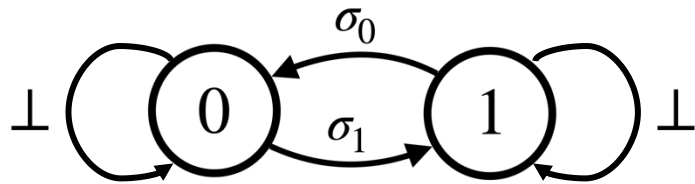
(R6) Standard regularizations have various influences.



# Preliminary interpretability results

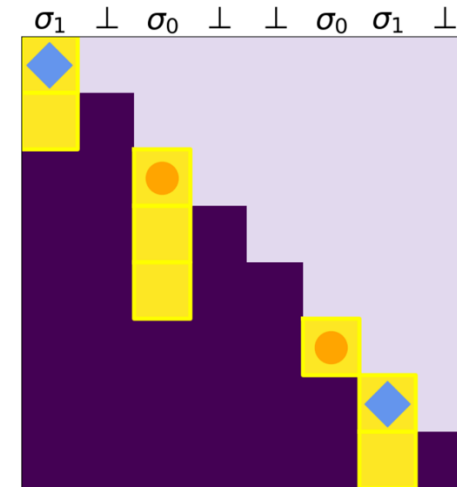
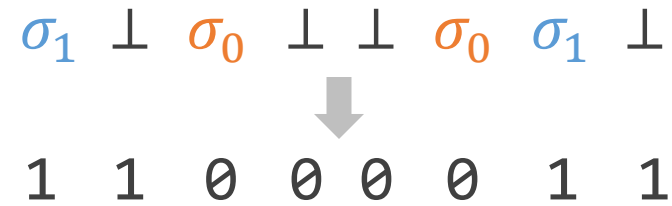
Simpler setup: flip-flop monoid

- $w0 = \sigma_0, w1 = \sigma_1, i = \perp$ ; read at each step.



Solvable by 1-layer 1-head Transformers.

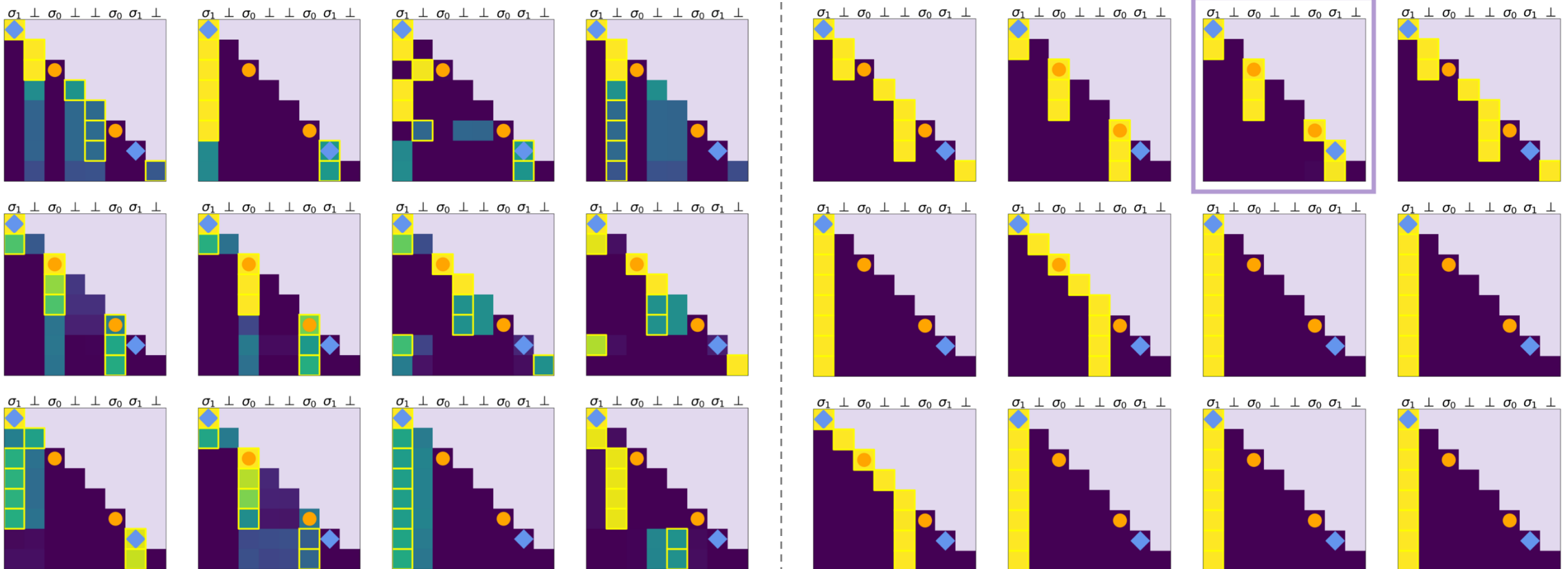
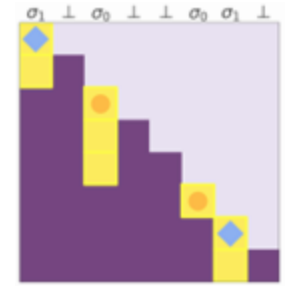
- 1-sparse attention: on the closest  $0,1$ .





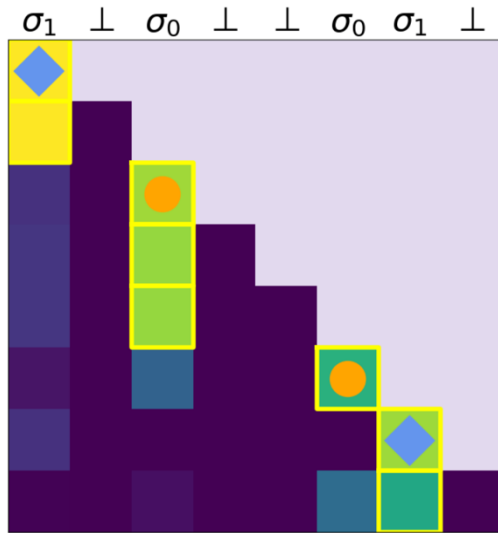
# What solutions are found?

6-layer 8-head ... normal (left) vs attention-sharpened (right)

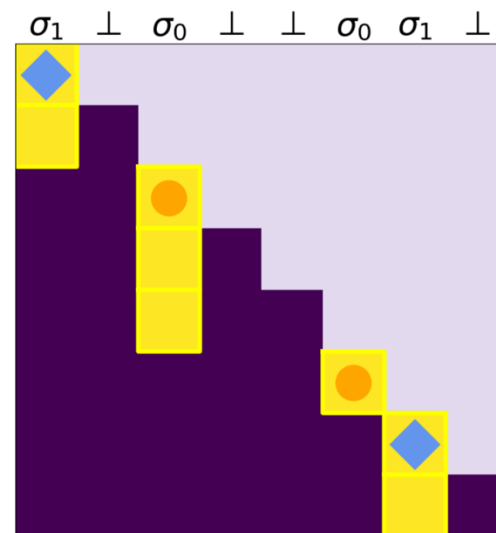


# What solutions are found?

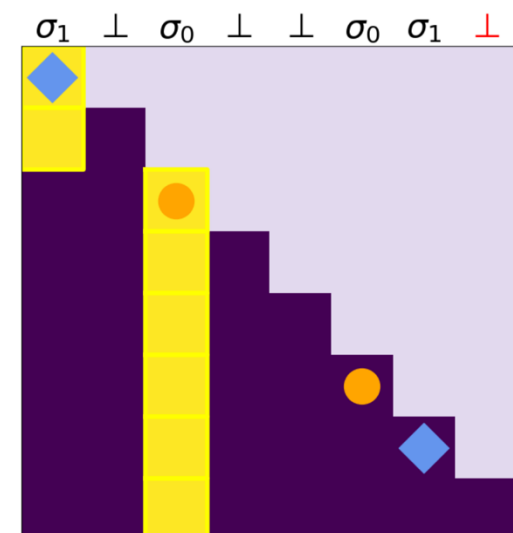
1-layer 1-head: normal vs attention-sharpened.



(a) normal



(b) sharpened 1



(c) sharpened 2

*other dense/sparse patterns exist*

wrong prediction!